

Computational
Integer Programming

W 11

Ralf Borndörfer

2. Models for the TSP

2.1. The Traveling Salesman Problem

Pf. 2.1.1. (Traveling Salesman Problem, TSP):

Input: Complete Digraph $D = (V, A)$ with $V = \{1, \dots, n\}$, $n \geq 3$ nodes and $M = n(n-1) = n^2 - n$ arcs, costs $c_{ij} \in \mathbb{Q}$ for all $ij \in A$.

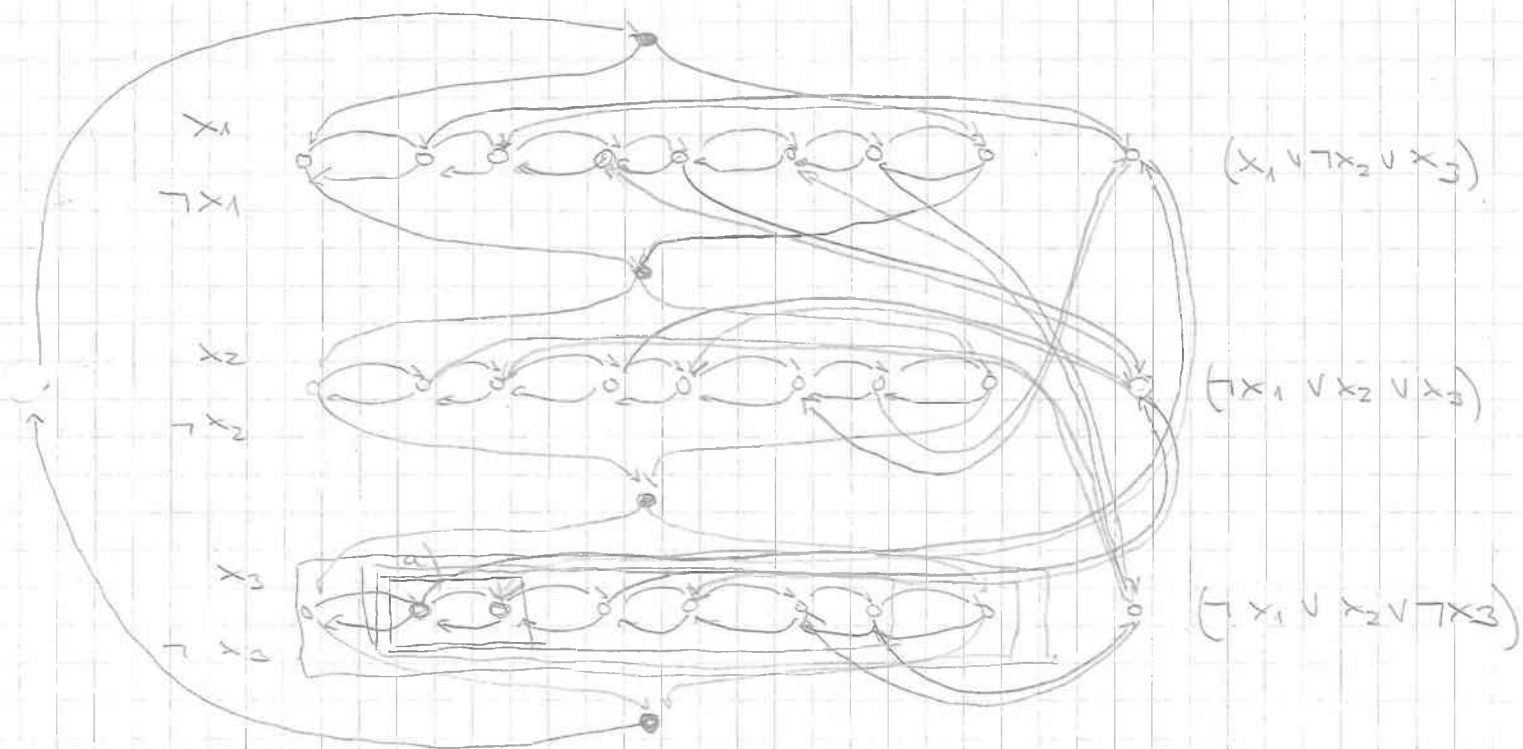
Output: Tour, i.e., closed sequence of n arcs $T = (v_1, v_2, v_2, v_3, \dots, v_{n-1}, v_n, v_n, v_1) \in A^n$,
 st. $\{v_1, \dots, v_n\} = V$, of min. cost $c(T) = \sum_{i=1}^n c_{v_i, v_{i+1}}$.

Remark 2.1.2: $n \geq 3$ rules out 2-node ping-pong-tour, which often cause technical difficulties.

Theorem 2.1.3: The TSP is NP-hard.

Proof (Sketch): We reduce SAT to TSP (actually: MCP)

Example: $(x_1 \vee \neg x_2 \vee x_3) \wedge (\neg x_1 \vee x_2 \vee x_3) \wedge (\neg x_1 \vee x_2 \vee \neg x_3)$



SAT \rightarrow TSP: \checkmark

TSP \rightarrow SAT: b) \bullet nodes \Rightarrow start direction for variable gadgets.

a) Var. gadgets can only be traversed left-right or right-left, consider second to third node first, ..., to last node, therefore also first node. c) Remaining nodes follow. \square

22. The Dantzig-Fulkerson-Johnson Formulation (DFJ)

Def. 22.1 (Dantzig-Fulkerson-Johnson-TSP Formulation):

- (DFJ) min $c^T x$
- (i) $x(S^+(i)) = 1 \quad \forall i \in V$ out-degree constraints
 - (ii) $x(S^-(i)) = 1 \quad \forall i \in V$ in-degree
 - (iii) $x(A(W)) \leq |W| - 1 \quad \forall \emptyset \subsetneq W \subsetneq V$ subtour elimination constraints
(Clique constraints)
 - (iv) $0 \leq x_{ij} \leq 1 \quad \forall ij \in A$ bounds
 - (v) $x_{ij} \in \mathbb{Z} \quad \forall ij \in A$ integrality constraints

(i), (ii) are also called assignment constraints or 2-matching constraints
(Assignment \rightarrow Matching relation)

Def. 22.2. (DFJ) (i), (ii), (iv), (v) define the assignment of
a) DFJ has $O(n^2)$ variables and $O(2^n)$ constraints
b) DFJ has $O(n^2)$ variables and $O(2^n)$ constraints
2-matching relation of the TSP.

Obs. 22.3 (Outer form of the SECS):

$$x(A(W)) \leq |W| - 1 \Leftrightarrow x(W: V \setminus W) \geq 1 \quad \forall \emptyset \subsetneq W \subsetneq V$$

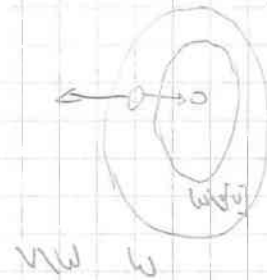
Proof: $x(A(W)) \leq |W| - 1$

$$\Leftrightarrow |W| - x(A(W)) \geq 1$$

$$\Leftrightarrow \sum_{v \in W} x(S^+(v)) - \sum_{v \in W} x(S^-(v: W)) \geq 1$$

$$\Leftrightarrow \sum_{v \in W} x(S^+(v: V \setminus W)) \geq 1$$

$$\Leftrightarrow x(W: V \setminus W) \geq 1$$



□

Rem. 22.4: The outer form of the SECS is easier to separate because the rhs is constant.

Obs. 22.5: The separation problem for SECS is a min-cut problem and can be solved in polynomial time.

Proof: $\exists \emptyset \subsetneq W \subsetneq V: x(W: V \setminus W) < 1$

$$\Leftrightarrow \exists \substack{S \subseteq V \\ W \subseteq W} \substack{S \neq t \\ W \subseteq W}: x(S: t) < 1. \quad \square$$

Rem. 22.6: There are better algorithms to separate SECS than trying all pairs $S \neq t$.

Cor. 2.2.7.: The LP-relaxation of $[DF]$ can be solved in polynomial time.

Def. 2.2.8.: (LP / IP-value): Let IP be an integer program. Denote by
 $v_{LP}(IP)$ optimal value of the LP-relaxation of IP (prec. $\pm \infty$)
 $v_{IP}(IP)$ " " of IP (")

Prop. 2.2.9.: Let $AP = [DF](A), (b), (i^0), (u)$ the ass. data of $[DF]$. Then
 $v_{LP}(AP) \stackrel{(i)}{=} v_{IP}(AP) \leq v_{LP}([DF]) < v_{IP}([DF])$.

Proof. (i) AP is integer. □

2.3 The Miller-Tucker-Zemlin-Formulation (MTZ)

Def. 2.3.1. (Miller-Tucker-Zemlin TSP-Formulation):

(MTZ) min $\sum c_j x_j$

(i) $x(S^+(i)) = 1 \quad \forall i \in V$

(ii) $x(S^-(i)) = 1 \quad \forall i \in V$

For Prop 2.3.4

(iii) $u_i - u_j + (n-1)x_{ij} \leq n-2 \quad \forall i \neq j, j \neq 1$

$2 \leq i+j \leq n$

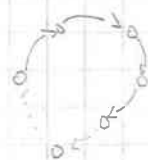
(iv) $0 \leq x_{ij} \leq 1 \quad \forall ij \in A$

(v) $0 = u_1 \leq u_i \quad \forall i \in V \setminus \{1\}$

$0 \leq u_i, i=2, \dots, n$

(vi) $x_{ij} \in \mathbb{Z} \quad \forall ij \in A$

Prop. 2.3.2. MTZ is a correct formulation for the TSP.



Proof: " \Leftarrow " Let X be a solution of $[DF]$.

$$u_i + (n-1)x_{ij} - (n-2) \leq \begin{cases} u_i + 1, & \text{if } x_{ij} = 1 \\ u_i - n + 2, & \text{if } x_{ij} = 0 \end{cases} \leq u_j$$

$$u_i \leq n-1 \Rightarrow u_i - n + 2 \leq 1$$

i.e., u_i can be increased along the arcs of the graph (from 0, 1, ..., $n-1$), except for the last arc.

" \Rightarrow " Let X, \bar{u} be a solution of MTZ. w.l.o.g. $\bar{u} \in \mathbb{Z}$ (otherwise $\lfloor \bar{u} \rfloor$ is also a solution) and \bar{u} is minimal $\Rightarrow \bar{u}$ is a permutation of $0, \dots, n-1$. □

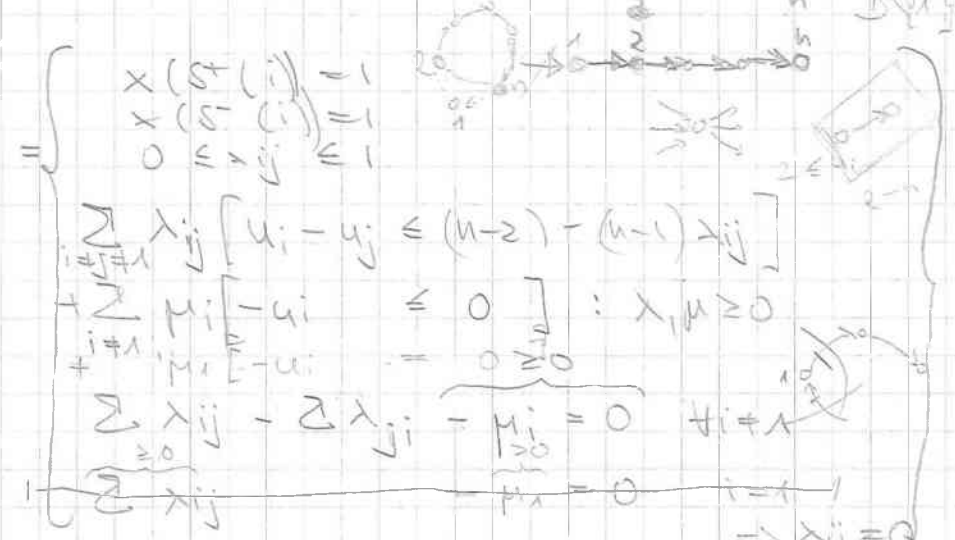
Rem. 2.3.3 MTZ has $O(n^2)$ variables and $O(n^2)$ constraints.

Prop. 2.3.4. $v_{LP}(MTZ) \leq v_{LP}([DF])$.

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Proof:

a) $\prod_{i,j} x_{ij} \{ (M^T z)(i) - u_i \}$



$$= \begin{cases} x(\delta^+(i)) = 1 \\ x(\delta^-(i)) = 1 \\ 0 \leq x_{ij} \leq 1 \\ \sum_{i \neq j} \lambda_{ij} [u_i - u_j \leq (n-2) - (n-1) \lambda_{ij}] \\ + \sum_{i \neq 1} \mu_i [-u_i \leq 0] : \lambda, \mu \geq 0 \\ + \sum_{i \neq 1} \mu_i [-u_i = 0] \\ \sum_{i \neq 1} \lambda_{ij} - \sum_{j \neq 1} \lambda_{ji} - \mu_i = 0 \quad \forall i \neq 1 \\ \sum_{i,j} \lambda_{ij} = 0 \end{cases}$$

$$= \begin{cases} x(\delta^+(i)) = 1 \\ x(\delta^-(i)) = 1 \\ 0 \leq x_{ij} \leq 1 \\ \sum_{i \neq j} \lambda_{ij} [x_{ij} \leq \frac{n-2}{n-1}] : \lambda^T u \geq 0, \lambda \geq 0 \\ \lambda = (\lambda_{ij})_{i,j \neq 1}, M \text{ arc-node inc. matrix of } \mathcal{D} \setminus \{1\} \end{cases}$$

$$= \text{conv} \{ x^C : C \text{ an cycle in } \mathcal{D} \setminus \{1\} \} = \begin{cases} x(\delta^+(i)) = 1 \\ x(\delta^-(i)) = 0 \\ 0 \leq x_{ij} \leq 1 \\ x(C) \leq |C| \frac{n-2}{n-1} = |C| - \frac{|C|}{n-1}, C \neq 1 \end{cases}$$

$$x(C) \leq x(A(C)) \leq |C| - 1 \leq |C| - \frac{|C|}{n-1} \Rightarrow \begin{cases} x(\delta^+(i)) = 1 \\ x(\delta^-(i)) = 1 \\ 0 \leq x_{ij} \leq 1 \\ x(A(C)) \leq |C| - 1, C \neq 1 \end{cases} \geq \{ (C \neq 1) | (i) - (ii) \}$$

b) Let $\mathcal{D} = (V, A)$ be a digraph, $M = M(A)$ its arc-node inc. matrix.

$\{ \lambda^T M \geq 0, \lambda \geq 0 \} = \text{conv} \{ C : C \text{ an cycle in } \mathcal{D} \}$

" \supseteq ": $\lambda^T M \mathbf{1} = \lambda^T \mathbf{0} = 0 \Rightarrow \{ \lambda^T M \geq 0, \lambda \geq 0 \} = \{ \lambda^T M = 0, \lambda \geq 0 \}$

Let $\bar{\lambda} \in \{ \lambda^T M = 0, \lambda \geq 0 \}$. w.l.o.g. $\text{supp}(\bar{\lambda})$ 2-arc-connected. (otherwise $\bar{\lambda} = \bar{\lambda}^1 + \bar{\lambda}^2$, as $\bar{\lambda}^1 M_i \neq 0$ for $\text{deg}_i(\text{supp}(\bar{\lambda}^1)) = 1$).

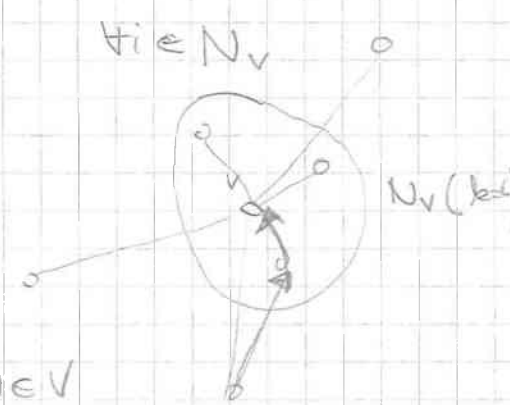
$\bar{\lambda}$ can be subdivided into a sum of directed cycles. \square

2.4. The Van Veyse-Wolsey-Formulation (VW)

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Def. 2.4.1 (Van Veyse-Wolsey-TSP Formulation)

- (VW_k) min $c^T x$
- (i) $x(\delta^+(i)) = 1 \quad \forall i \in V$
 - (ii) $x(\delta^-(i)) = 1 \quad \forall i \in V$
 - (iii) $u_i + 1 \leq u_j + (1 - x_{ij})(u-1) \quad \forall ij \in A, j \neq i$
 - (iv) $0 \leq x_{ij} \leq 1 \quad \forall ij \in A$
 - (v) $0 = u_1 \leq u_i \quad \forall i \in V, i \neq 1$
 - (vi) $x_{ij} \in \mathbb{Z} \quad ij \in A$
 - (vii) $w^v(\delta^-(i)) - w^v(\delta^+(i)) = \begin{cases} 0, & i \neq v \\ 1, & i = v \end{cases} \quad \forall i \in N_v$
 - (viii) $w_{ij}^v \leq x_{ij} \quad \forall v \in V, ij \in A_v$
 - (ix) $w_{ij}^v \geq 0 \quad \forall v \in V, ij \in A$



Let $k \in [1, n-1]$ and

$$N_v := \text{neighborhood of size } k \text{ around } v, \text{ i.e., the set of the } k \text{ nodes closest to } v \text{ (including } v \text{) and } A_v = \bigcup_{j \in N_v} \delta^+(j) \cup \bigcup_{j \in N_v} \delta^-(j).$$

be a local neighborhood of size k around v , i.e., the set of the k nodes closest to v (including v) and $A_v = \bigcup_{j \in N_v} \delta^+(j) \cup \bigcup_{j \in N_v} \delta^-(j)$.

Def 2.4.2: (VW_k) (i), (ii), (vi) = (MIZ), (VW_k) (vii), (ix) induce for each v a flow of value 1 from N_v to v .

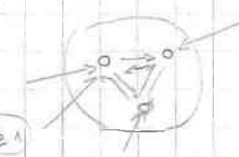
Obs 2.4.3: (VW_k) has $O(n^2 + n(k^2 + 2kn)) = O(kn^2)$ variables and $O(2n + n^2 + 2n(n-1) + nk + 2n^3) = O(n^3)$ constraints.

Prop. 2.4.4 For each $u \in N_v, u \neq v$, holds

$$x(\delta^+(u)) \geq 1.$$

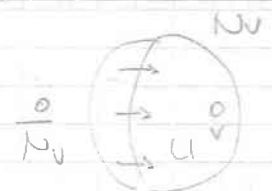
Proof:

$$\begin{aligned} x(\delta^+(u)) &= x(\delta^-(u)) \geq w^v(\delta^-(u)) = w^v(\bar{u}:u) \\ &= \underbrace{\sum_{j \in A} w^v(\bar{u}:j)}_{= \sum_{j \in A} w^v(\delta^-(j))} + \underbrace{\sum_{j \in A} w^v(u:j)}_{= \sum_{j \in A} w^v(j:u)} - \underbrace{\sum_{j \in A} w^v(u:j)}_{= \sum_{j \in A} w^v(j:\bar{u})} - 0 \\ &\geq \sum_{j \in A} [w^v(\delta^-(j)) - w^v(\delta^+(j))] = 1 \quad \square = \sum_{j \in A} w^v(\delta^+(j)) \quad \textcircled{5} \end{aligned}$$



Prop. 2.4.5: $\tau(VW_{n-1})|_X \cong \tau(DF)$.

Proof: " \subseteq ": Prop 2.4.4



" \supseteq ": Let $\bar{x} \in \tau(DF)$. Consider \bar{x} as capacities in D , choose $t \in V$,
 $\Rightarrow \bar{x}(\bar{u}:u) \geq 1 \quad \forall v \in U \in N_v$ S with max. flow

\Rightarrow the capacity of any s, t cut ≥ 1
 MFC $\Rightarrow \exists$ s, t -flow w^v of value 1
 $\Rightarrow w^v(\delta^-(i)) - w^v(\delta^+(i)) = \begin{cases} 0, & i \neq t \\ 1, & i = t \end{cases}$

$0 \leq w^v \leq \bar{x}$. \square

Cor. 2.4.6: $v_{LP}(MFE) \stackrel{N_v = \sum_{i,j} t_{ij} = 1}{=} v_{LP}(WU_1) \leq \dots \leq v_{LP}(WU_{n-1}) \leq v_{LP}(DF)$.

2.5 The Multiflow or Flow-Transulation (MF)

Def. 2.5.1 (Multiflow-TSP-Transulation): Let $S \in V$.

(MF_S) min $\sum x$

$x(\delta^+(i)) = 1 \quad \forall i \in V$

$x(\delta^-(i)) = 1 \quad \forall i \in V$

$w^t(\delta^+(i)) - w^t(\delta^-(i)) = \begin{cases} 1 & i = S \\ 0 & i \neq S, t \\ -1 & i = t \end{cases} \quad \forall t \in V, t \neq S, i \in V$

$0 \leq w_{ij}^t \leq x_{ij} \quad \forall t \in V, t \neq S, ij \in A$

$x_{ij} \in \mathbb{Z} \quad \forall ij \in A$

Prop. 2.5.1: $x(\delta^+(W)) \geq 1 \quad \forall \emptyset \neq W \neq V$.

Proof: $x(\delta^+(W)) = x(\delta^-(W)) = x(\delta^+(\bar{W})) \Rightarrow$ w.l.o.g. $S \in W$.

Choose $t \in \bar{W}$. Then w^t is s, t -flow of value 1 in D with cap. x

MFC $\Rightarrow x(\delta^+(W)) = x(\bar{v}:u) \geq 1$.

Prop. 2.5.2: $\tau(MF_S)|_X = \tau(DF)$.

Proof: Analogous to the one of Prop. 2.4.5. \square

Cor. 2.5.3: $v_{LP}(MFE) = v_{LP}(WU_1) \leq \dots \leq v_{LP}(WU_{n-1}) \leq v_{LP}(MF) = v_{LP}(DF)$

Obs. 2.5.4: (MF_S) has $O(n^3)$ variables and $O(n^3)$ constraints,

i.e., there is a TSP formulation of polynomial size that provides the DF LP-bound.

Prop. 26.4. $P(\text{FGR})|_X = \{ x(A) = n, -x(S^+(A)) + n x(S^-(A)) = n-1, -x(1:S) + n x(S:1) + 2x(S:S \setminus \{1\}) - (n-1)x(S \setminus \{1\}:S) \leq |S| \}$
 $\forall \emptyset \neq S \subseteq V \setminus \{1\}, x \geq 0 \}$

Proof. $P(\text{FGR})|_X = \{ x: \lambda(i) + \sum_i \mu_i(ii) + \sum_{ij \in A} v_{ij} \tau(ij) + \sum_{ii} \pi(ii) \}$
 $(\lambda, \mu, \tau, \pi)^T \begin{pmatrix} \Delta^T & \Delta^T & 0 \\ A_1 & A_2 & 0 \\ -I & 0 & 0 \\ 0 & -I & 0 \\ L_1 & L_2 & I \end{pmatrix} = (0, 0, 0)^T, v \geq 0 \}$

$(\lambda, \mu, \tau, \pi)^T \begin{pmatrix} \Delta^T & \Delta^T & 0 \\ A_1 & A_2 & 0 \\ -I & 0 & 0 \\ 0 & -I & 0 \\ L_1 & L_2 & I \end{pmatrix} = (0, 0, 0)^T \Leftrightarrow \begin{cases} (\pi_{ii}) = \lambda \Delta - \mu - v_1, v_1 \geq 0 \\ (\pi_{ii}) = \lambda \Delta + n\mu - v_n, v_n \geq 0 \\ (\pi_{ij}) = \lambda \Delta + 2\mu^T \mu - v_2, v_2 \geq 0 \end{cases}$
 $\Leftrightarrow \lambda \Delta + k\mu^T \mu - v_k - (\lambda \Delta + 2\mu^T \mu - v_2) = 0, k=3, \dots, n-1$
 $\Leftrightarrow (k-2)\mu^T \mu - v_k + v_2 = 0, k=3, \dots, n-1$
 $\Leftrightarrow (k-2)\mu^T \mu + v_2 = v_k \geq 0, k=3, \dots, n-1$

$\Leftrightarrow (\pi_{ii}) = \lambda \Delta - \mu - v_1, v_1 \geq 0, (n-3)\mu^T \mu + v_2 \geq 0$
 $(\pi_{ii}) = \lambda \Delta + n\mu - v_n, v_n \geq 0, v_2 \geq 0$
 $(\pi_{ij}) = \lambda \Delta + 2\mu^T \mu - v_2$

It holds

$\{ \rho \mu^T \mu + v_2 \geq 0, v_2 \geq 0 \} = \text{lin} \begin{pmatrix} \Delta \\ 0 \end{pmatrix} + \text{conc} \left\{ \begin{pmatrix} 0 \\ e_{ij} \end{pmatrix} \right\}_{\substack{j \in A \\ i, j \neq 1}} + \text{conc} \left\{ \begin{pmatrix} X_S \\ P X_S^T(S) \end{pmatrix} \right\}_{\substack{S \subseteq V \setminus \{1\} \\ 1 \leq |S| \leq n-2}} + \text{conc} \left\{ \begin{pmatrix} -X_S \\ P X_S^T(S) \end{pmatrix} \right\}_{\substack{S \subseteq V \setminus \{1\} \\ 1 \leq |S| \leq n-2}}$

$\Rightarrow \{ (\lambda, v_1, v_n, \mu, v_2) : (n-3)\mu^T \mu + v_2 \geq 0, v_2 \geq 0, v_1 \geq 0, v_n \geq 0 \}$
 $= \text{lin} \lambda \times \text{conc}_{i \neq 2} \{ e_i \} \times \text{conc}_{i \neq 2} \{ e_i \} \times \left[\text{lin} \begin{pmatrix} \Delta \\ 0 \end{pmatrix} + \text{conc} \left\{ \begin{pmatrix} 0 \\ e_{ij} \end{pmatrix} \right\} + \text{conc} \left\{ \begin{pmatrix} X_S \\ P X_S^T(S) \end{pmatrix} \right\} + \text{conc} \left\{ \begin{pmatrix} -X_S \\ P X_S^T(S) \end{pmatrix} \right\} \right]$

i.e., the dual cone is generated as follows:

- i) $\lambda = \pm 1, \mu = 0, (v_1, v_n) = 0, v_2 = 0$
- ii) $\lambda = 0, \mu = 0, (v_1, v_n) = e_i, v_2 = 0, i = 1, \dots, 2(n-1)$
- iii) $\lambda = 0, \mu = \pm \Delta, (v_1, v_n) = 0, v_2 = 0$
- iv) $\lambda = 0, \mu = 0, (v_1, v_n) = 0, v_2 = e_{ij}, j \in A, i, j \neq 1$
- v) $\lambda = 0, \mu = X^S, (v_1, v_n) = 0, v_2 = (n-3)X(S \setminus \{1\}:S), S \subseteq V \setminus \{1\}, 1 \leq |S| \leq n-2$
- vi) $\lambda = 0, \mu = -X^S, (v_1, v_n) = 0, v_2 = (n-3)X(S: S \setminus \{1\}), S \subseteq V \setminus \{1\}, 1 \leq |S| \leq n-2$

This produces the following constraints:

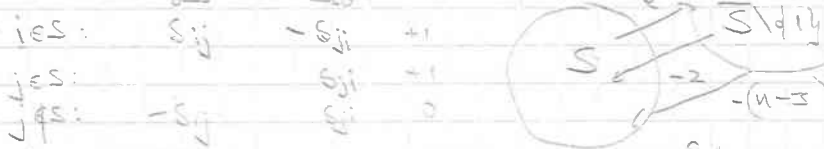
i) $\lambda = 1 \Rightarrow \pi = \mathbb{1} \Rightarrow \sum \pi_{ij}(v) \Leftrightarrow \boxed{x(A) = n}$

ii), iv) $(v_1, v_n, v_2) = e_{ij} \rightarrow \pi_{ij} = -e_{ij} \Rightarrow -x_{ij} \leq 0 \Leftrightarrow \boxed{x_{ij} \geq 0 \forall ij \in A}$

iii) $\mu = \mathbb{1} \Rightarrow (\pi_{ii}) = -\mathbb{1}, (\pi_{i1}) = n\mathbb{1}, (\pi_{ij}) = 0 \Rightarrow \boxed{-x(S^+(A)) + nx(S^-(A)) = n-1}$

v) $\mu = X_S, v_2 = (n-3)X_{\bar{S} \setminus \{i\}} \Rightarrow (\pi_{ii}) = -X_{(1:S)}, (\pi_{i1}) = nX_{(S:1)}$

$$(\pi_{ij}) = \begin{cases} 0, & ij \in S \\ 2, & ij \in S^+(S), ij \neq 1 \\ -2, & ij \in S^-(S), ij \neq 1 \\ 0, & \text{else} \end{cases}$$



$\forall S \subseteq V \setminus \{i\}, 1 \leq |S| \leq n-1$

$\Rightarrow \boxed{-x(1:S) + nx(S:1) + 2x(S:S \setminus \{i\}) - (n-1)x(\bar{S} \setminus \{i\}:S) \leq |S|}$

vi) $\mu = -X_S, v_2 = (n-3)X_{(S:S \setminus \{i\})} \Rightarrow (\pi_{ii}) = X_{(1:S)}, (\pi_{i1}) = -nX_{(S:1)}$

$$(\pi_{ij}) = \begin{cases} 0, & ij \in S \\ 2, & ij \in S^+(S), ij \neq 1 \\ 2, & ij \in S^-(S), ij \neq 1 \\ 0, & \text{else} \end{cases}$$



$\forall S \subseteq V \setminus \{i\}, 1 \leq |S| \leq n-1$

$\Rightarrow \boxed{x(1:S) - nx(S:1) + 2x(S:S \setminus \{i\}) - (n-1)x(S:\bar{S} \setminus \{i\}) \leq -|S|}$
 $-x(S^+(A)) + nx(S^-(A)) = n-1$

$x(1:\bar{S} \setminus \{i\}) - nx(\bar{S} \setminus \{i\}:1) + 2x(\bar{S} \setminus \{i\}:S) - (n-1)x(S:\bar{S} \setminus \{i\}) \leq |S| - 1$
 $\Leftrightarrow (*) \text{ for } S = \bar{S} \setminus \{i\}. \quad \square$

Prop 2.65: The system $(FAC|x)$

- (i) $x(A) = n$
- (ii) $-x(S^+(A)) + nx(S^-(A)) = n-1$
- (iii) $-x(1:S) + nx(S:1) + 2x(S:S \setminus \{i\}) - (n-1)x(S:\bar{S} \setminus \{i\}) \leq |S| \forall S \subseteq V \setminus \{i\}, 1 \leq |S| \leq n-1$
- (iv) $x \geq 0$
 $x \in \mathbb{Z}^A$

is a valid \rightarrow formulation.

Proof: $n \underbrace{x(S^-(A))}_{\geq 2} - \underbrace{x(S^+(A))}_{\leq x(A) \leq n} \geq 2n - n \geq n \not\leq \Rightarrow x(S^-(A)) = x(S^+(A)) = 1$
 Supp. $x(S^+(i)) = 0, i \neq 1$, let $S = V \setminus \{1, i\}, \bar{S} = \{1, i\}$.
 $\Rightarrow -x(1:S) + nx(S:1) - (n-1)x(\bar{S} \setminus \{i\}:S) + 2x(S:\bar{S} \setminus \{i\}) \leq |S|$
 $\Rightarrow -x(1:S) + n + 2x(S:i) = 0 \leq |S| \leq n-1 \not\leq$

$$\Rightarrow x(S^+(i)) \geq 1 \quad \forall i \neq 1$$

$$-(n-1) + (n-1)$$

$$\text{For } S = \{i, j\}, i \neq 1:$$

$$-x(1:i) + nx(i:1) + 2x(i:V \setminus \{1, i, j\}) - (n-1)x(V \setminus \{1, i, j\}:i) \leq 1$$

$$\Rightarrow \underbrace{-(n-1)x(S^-(i))}_{=1} + \underbrace{2x(S^+(i))}_{=2} + \underbrace{(n-2)(x_{ji} + x_{ij})}_{=2} \leq 1$$

$$\Rightarrow x(S^-(i)) \geq 1 \quad \forall i \neq 1$$

$$\Rightarrow x(S^+(i)) = x(S^-(i)) = 1 \quad \forall i$$

$\Rightarrow \text{supp}(x) = V$ directed.



Let S' be the node set of the directed graph denoted by 1, $S = S' \cup \{1\}$.

$$\Rightarrow -x(1:S) + nx(S:1) + 2x(S:S \setminus \{1\}) - (n-1)x(S \setminus \{1\}:S) = -1 + n \leq |S| \leq n-2$$

□

Prop 26.6 $\mathcal{P}(\text{DF}) \not\subseteq \mathcal{P}(\text{FAG}) \setminus x$.

Proof: Let $\bar{x} \in \mathcal{P}(\text{DF}) \Rightarrow x(S^+(i)) = x(S^-(i)) = 1 \Rightarrow \text{FAG}(x)(i), (i)$.

$$\bar{x}(S:S) = \bar{x}(S:S) \leq |S|$$

$$-\bar{x}(1:S) + n\bar{x}(S:1) + 2\bar{x}(S:S \setminus \{1\}) - (n-1)\bar{x}(S \setminus \{1\}:S) \leq |S|$$

$$x(S \setminus \{1\}:S) + x(S \setminus \{1\}:1) \geq 1$$

$$-(x(S \setminus \{1\}:1) + x(S:1)) = 1$$

$$\Rightarrow -\bar{x}(S:S) + 2\bar{x}(S:S) + (n-2)[\bar{x}(S:1) - \bar{x}(S \setminus \{1\}:S)] \leq |S|$$

$$x(S \setminus \{1\}:S) \geq x(S:1)$$

$\Rightarrow \text{FAG}(x)(i)$ holds.

$$\text{Let } \bar{x}_{ij} = \begin{cases} 1/n, & i, j \in S^-(1) \\ 0, & i, j \in S^+(1) \\ \frac{(n^2-n+1)}{n(n-1)(n-2)}, & i, j \in A \setminus S(1) \end{cases}$$

$\Rightarrow \bar{x} \in \mathcal{P}(\text{DF})$, but

$$(i) \bar{x}(A) = \frac{n-1}{n} + \frac{(n-2) \cdot (n^2-n+1)}{n(n-1)(n-2)} = n$$

$$(ii) -\bar{x}(S^+(1)) + n\bar{x}(S^-(1)) = n \frac{(n-1)}{n} = n-1$$

$$(iii) -\underbrace{x(1:S)}_{=0} + \underbrace{nx(S:1)}_{=|S|} + 2x(S:S \setminus \{1\}) - (n-1)x(S \setminus \{1\}:S) \leq |S|$$

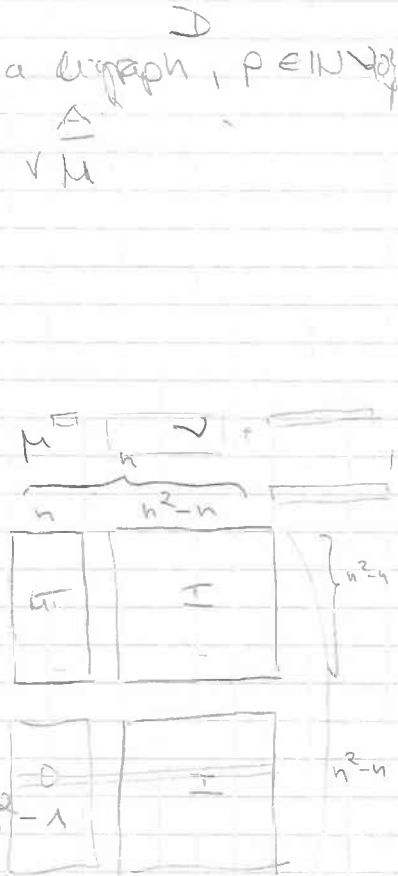
$$= \underbrace{x(S \setminus \{1\}:S)}_{=|S|} - \underbrace{(n-2)x(S \setminus \{1\}:S)}_{\leq 0}$$

Prop. 2.67 Let M be the node-arc incidence matrix of a digraph, $p \in \mathbb{N}^{V \times V}$

$$C = \left\{ (u^T, v) : p u^T M + v^T \geq 0, v \geq 0 \right\}$$

is generated by the following vectors:

- i) $(\pm \mathbb{1}^T, 0)$
- ii) $(0, p e_i)$ $\forall i \in V$
- iii) $(X_S, p X_{(S, \bar{S})})$ $\forall S \subseteq V, 1 \leq |S| \leq n-1$
- iv) $(-X_S, p X_{(\bar{S}, S)})$ $\forall S \subseteq V, 1 \leq |S| \leq n-1$



Proof:

$$C = \left\{ \begin{pmatrix} p M^T & I \\ 0 & I \end{pmatrix} \begin{pmatrix} u \\ v \end{pmatrix} \geq 0 \right\} = \left\{ B \begin{pmatrix} u \\ v \end{pmatrix} \geq 0 \right\}$$

$$\text{rank } M = \text{rank } M^T = n-1 \Rightarrow \text{rank } B = n(n-1) + n-1 = n^2 - 1$$

\Rightarrow dim of duality space of $C = 1 \Rightarrow \text{lin}(\mathbb{1}^T, 0) \subseteq C$.

(u, v) extreme ray of $C \Leftrightarrow \exists (n-2) \times n$ submatrix B^* of B such that

$$B^* \begin{pmatrix} u \\ v \end{pmatrix} = 0, (u, v) \neq 0, \text{ support of } (u, v) \text{ is } \text{supp } B^*$$

$$\Rightarrow B^* \begin{pmatrix} u \\ v \end{pmatrix} = \begin{pmatrix} B_1 & f \end{pmatrix} \begin{pmatrix} u \\ v \end{pmatrix} = 0, \text{ rank } B_1 = \text{rank } B^* = n^2 - 2$$

$\forall f \hat{=} v$: i) $\forall ij = 0 \in \text{supp } B^* \Rightarrow 0^T \in B^* \Rightarrow \text{rank } B^* \leq n^2 - 3$

ii) $f=0 \Rightarrow (u, v) = (0, p e_i)$

iii) $f u_i - p u_j + v_j \in \text{supp } B^* \Rightarrow 0$

no square submatrix of B^* of rank $n^2 - 2$ contains all columns from M^T $\Rightarrow f \hat{=} p_i$

$f \hat{=} p_i \Rightarrow B_1 = \begin{pmatrix} A_0 & f \\ A_1 & 0 & I_1 \\ 0 & I_0 & 0 \end{pmatrix}$ $f = \begin{pmatrix} f_0 \\ f_1 \\ 0 \end{pmatrix}$ $n-2$ rows $\Rightarrow \text{rank } A_0 = n-2$
 $\Rightarrow w_{ij} = 0, ij \in \text{supp } I_0$

f in Fulkerson & Seymour

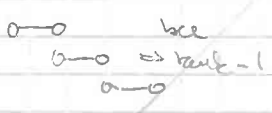
$\text{rank } A_0 = n-2 \Rightarrow \text{rank } (A_0, f_0) = n-2$ (max)

let $H = D(A_0, f)$. H has n nodes and contains

no cycles (otherwise $\text{rank } (A_0, f) < n-2$)

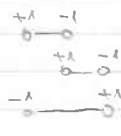
$\Rightarrow H$ contains an isolated node or 2 trees.


If j is isolated, set $S = \{j\}$ and



i) \mathbb{B}^k contains a zero column for $v_{ij} \Rightarrow (y, v) = (0, p e_i)$.

ii) $\mathbb{B}^k = \begin{pmatrix} A_0 & I & 0 \\ A_1 & 0 & I_1 \\ 0 & I_0 & 0 \end{pmatrix} \begin{matrix} \left. \vphantom{\begin{pmatrix} A_0 & I & 0 \\ A_1 & 0 & I_1 \\ 0 & I_0 & 0 \end{pmatrix}} \right\} n-2 \\ \left. \vphantom{\begin{pmatrix} A_0 & I & 0 \\ A_1 & 0 & I_1 \\ 0 & I_0 & 0 \end{pmatrix}} \right\} n^2 \end{matrix}$, rank $A_0 = n-2$ maximal

$\Rightarrow H = \mathcal{D}(A_0)$ does not contain a cycle  (otherwise low rank can not be maximal)

$\Rightarrow H$ is a forest , containing exactly 2 trees on node

sets $S, T, |S|, |T| \geq 2, S \cup T = V, v_{ij} = 0 \ \forall ij \in I_0$

$\Rightarrow u_i = \alpha, i \in S, u_j = \beta, i \in T, \begin{cases} \alpha - \beta + v_{ij} \geq 0, & ij \in T:S \\ \beta - \alpha + v_{ij} \geq 0, & ij \in S:T \end{cases}$

$\alpha = \beta \Rightarrow (y, v) = (\alpha, 0) \in \text{ker } \mathbb{B}$ (already known)

$\alpha > \beta \Rightarrow v_{ij} = \alpha - \beta \ \forall ij \in T:S = \text{supp } A_1$

A solution with minimum support has

$\alpha = 0, \beta = -1, v_{ij} = 1 \ \forall ij \in T:S$ or

$\alpha = 1, \beta = 0, v_{ij} = 1 \ \forall ij \in T:S. \quad \square$

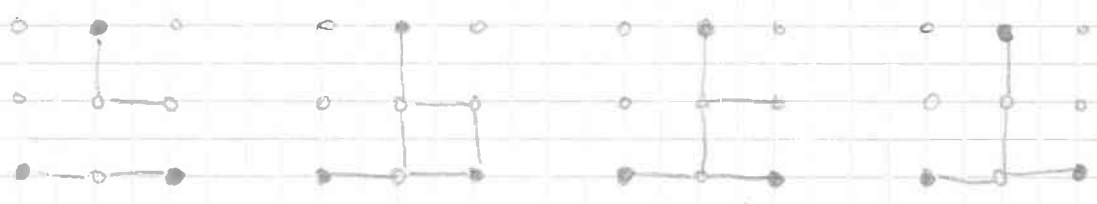
IP Formulations for the (Undirected) Steiner Tree Problem



Def. 1 (Steiner Tree Problem): Let $G=(V,E)$ be a graph, $R \subseteq V$ a set of terminals, and $V \setminus R$ a set of Steiner nodes. An edge set $F \subseteq E$ of G is Steiner, if it contains a tree that spans R . It is a Steiner tree if it does not contain a cycle.

Let $c \in \mathbb{Q}_+^E$ be nonnegative edge weights and $c(F) = \sum_{e \in F} c_e$. Then $\min c(F)$, F Steiner tree in G (w.r.t R) is the Steiner Tree Problem (STP) \square

Ex. 2:



a) not Steiner b) Steiner c) Steiner tree d) inclusion with Steiner Tree \square

Exam 3 a) STP has appl. in network design, e.g. VLSI design. b) Using simple preprocessing argument, one can assume w.l.o.g. \square

i) G is 2-edge-connected ii) G is 2-node-connected \square



Thm. 4 (Complexity of the STP, see e.g. Feo [2003]):

- a) The STP is strongly NP-hard.
- b) The STP can be solved in polynomial time for i) $R=V$ (Spanning tree problem), ii) $|R|=1$, iii) $|R|=2$ (Shortest path problem), iv) $|R|=3$ (there is at most one vertex with degree 3, find v that minimizes $\sum_{r \in R} \text{dist}(v,r)$), v) $|R| = \text{const}$ (dynamic prog. alg. by Dreyfus & Wagner [1972]). \square

Def. 5 (Steiner cut, Steiner partition): A Steiner partition is a partition V_1, \dots, V_k of V s.t. $V_i \cap R \neq \emptyset$, $i=1, \dots, k$. The edge set $S(V_1, \dots, V_k)$ is a Steiner multicut, for $k=2$ $S(V_1, V_2) = S(V_1)$ is a Steiner cut \square

Def. 6 (Notation): Let (IP) be an integer program. Denote by (IP_{LP}) its LP-relaxation, by $P(IP)$ the associated polyhedron and by $P_{int}(IP)$ the polyhedron associated with its LP-relaxation. \square

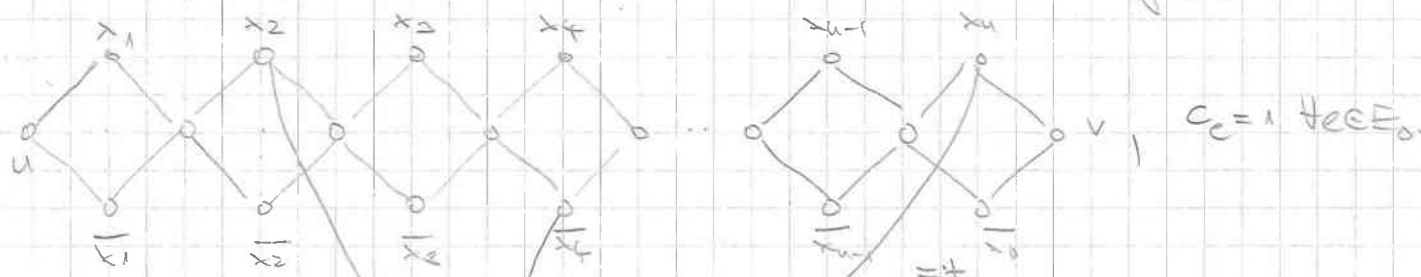
Thm.: STP is NP-hard.

Proof: SAT \leq STP

Consider an instance of SAT with clauses C_1, \dots, C_m on variables x_1, \dots, x_n

Consider an instance of STP with graph $G=(V, E)$ with weights $c \in \mathbb{Q}_+^E$,

terminals $R \subseteq V$, bound $B \in \mathbb{Q}_+$. Let $G_0 = (V_0, E_0)$ be the following graph:



Add for every C_i a clause gadget $G_i = (V_i, E_i)$ $c_e = 2n+1 \forall e \in E_i$.

Let $R := \{u, v, C_1, \dots, C_m\}$ $B := 2n + t \cdot m$, $G = \bigcup_{i=0}^m G_i$.

T.B.S.: \exists feasible x^0 $C_i \iff \exists$ s.t. $T \subseteq G, c(T) \leq B$.

" \Rightarrow ": Let $T = (u, \{x_i, \text{if } x_i^0 = 1\}, \dots, \{x_m, \text{if } x_m^0 = 1\}, v)$ a path

"reflecting" x^0 . Connecting to each C_i via one arc of length t produces s.t. T of weight $2n + tm = B$.

" \Leftarrow ": C_i is connected to P by ≥ 1 arc. Assume some C_i is connected by ≥ 2 arc $\Rightarrow c(T) \geq (m+1)t = t + mt = 2n + tm > B$.

\Rightarrow u and v are connected along G_0 by $\geq 2n$ edges

\Rightarrow by $2n$ edges $\Rightarrow x^0$ defined by $x_i^0 := 0$ if x_i left, 1 if x_i right

is a satisf. clause assignment. \square

Auction Game:

max $c^T y$

right!

$\sum_{i \in J} y_j \leq 1, i=1, \dots, m$

$y_j \in \{0, 1\}, j=1, \dots, n$

min $M \cdot \mathbb{1}'s - c^T y$

right!

$\sum_{i \in J} y_j + z_i = 1, i=1, \dots, m$

$y_j \in \{0, 1\}, j=1, \dots, n$

$z_i \in \{0, 1\}, i=1, \dots, m$

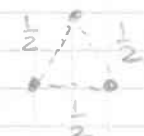
Def. 7 (Undirected Cut Formulation):

a) (STP^{UC}) with \vec{x}

- (i) $x(S(W)) \geq 1 \quad \forall \emptyset \neq W \cap R \neq R$ Undirected Cut Form. of the STP
Server cut constraint
- (ii) $x \geq 0$ non-neg. const.
- (iii) $x \in \mathbb{Z}^E$ int. const.

b) (STP^{UC+}) = (STP^{UC})

- (iv) $x(S(V_1, \dots, V_k)) \geq k-1 \quad \forall \text{ Server part } V_1, \dots, V_k$ Server part constraint \square

Ex. 8 (Server Partition):  Satisfies (STP^{UC}_{LP}), but not (STP^{UC+}_{LP}).

Prop. 9 (Undirected Cut Formulation):

a) (STP^{UC}) and (STP^{UC+}) are correct formulations of the STP ($P(\text{STP}^{\text{UC}}) = P(\text{STP}^{\text{UC+}})$)

b) $P_{LP}(\text{STP}^{\text{UC+}}) \subseteq P_{LP}(\text{STP}^{\text{UC}})$.
Suppose G is 2-edge and node-connected.

c) $\dim P(\text{STP}^{\text{UC}}) = |E|$.

- d) $x_e \geq 0$ defines a facet for $P(\text{STP}^{\text{UC}})$ for $|V| \geq 3$.
 - e) $x(S(W)) \geq 1$ defines a facet of $P(\text{STP}^{\text{UC}})$ iff $S(W)$ is minimal w.r.t. incl .
- Proof: a) b) clear, c) d) easy, e) f) see Chopra & Rao [1994a, b].
- f) $x(S(V_1, \dots, V_k)) \geq k-1$ defines a facet of $P(\text{STP}^{\text{UC}})$ if the graph $G - \bigcap_{i=1}^k V_i$ that arises from subtracting the sets V_i is 2-edge-connected and the graphs $G(V_i)$ are connected. \square

Def. 10 (Directed Cut Formulation): Associate with $G=(V,E)$ a directed graph $D=(V,A)$, $A=\{ij, ji: ij \in E\}$ and choose a root $v \in R$.

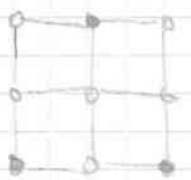
a) (STP^{DC}) with \vec{x}

- (i) $y(S^+(W)) \geq 1 \quad \forall v \in W \cap R \neq R$ directed Server cuts
- (ii) $y_{ij} + y_{ji} \leq x_{ij} \quad \forall ij \in E$ Coupling constraints
- (iii) $y \geq 0$ non-neg. "
- (iv) $x \geq 0$ non-neg. "
- (v) $y \in \mathbb{Z}^A$ int. "
- (vi) $x \in \mathbb{Z}^E$ int. " $\textcircled{2}$

b) $(STP^{\pm r}) = (STP^{unc}) (i), (ii), (v)$

Directed cut formulation of the SP

Ex 11:



undirected cut form.

directed cut form.

Prop. 12:

24.11.11

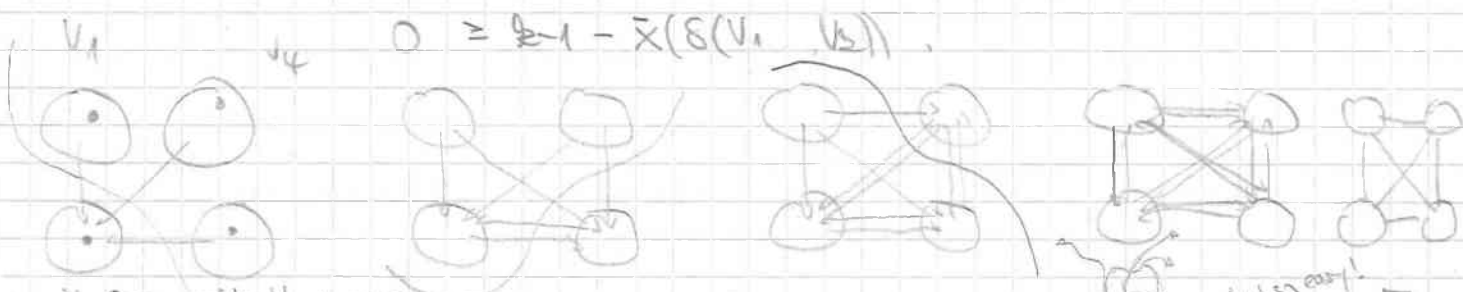
- a) $proj_Y T(STP^{unc}) = T(STP^{\pm r})$, b) $proj_{LP} T(STP^{unc}) = LP(STP^{\pm r})$.
- c) $proj_X T(STP^{unc}) = T(STP^{unc})$. d) $proj_X LP(STP^{unc}) \subseteq LP(STP^{\pm r})$.
- e) $V_{LP}(STP^{\pm r})$ does not depend on the choice of the root (for directed und. assoc. with undir. STPs).

Proof: a) b) c) clear. d) let $(\bar{x}, \bar{y}) \in LP(STP^{unc})$. We must show x satisfies $(STP^{\pm r})$ (i) and (iv).

$(STP^{\pm r})$ (i): $\bar{x}(\delta(w)) \geq \bar{y}(\delta^+(w)) + \bar{y}(\delta^-(w)) \stackrel{w.l.o.g.}{=} \bar{y}(\delta^+(w)) \geq 1$

$(STP^{\pm r})$ (iv): let V_1, \dots, V_k disjoint part., w.l.o.g. $v \in V_1$. Add the following ineq.:

$$\begin{aligned} \bar{y}(\delta^+(V \setminus V_i)) &\geq 1 & i=2, \dots, k \\ &\geq 0 & i \in \delta^+(V_i) \\ -\bar{y}_{ij} - \bar{y}_{ji} &\leq -\bar{x}_{ij} & ij \in \delta(V_1, \dots, V_k) \in E \end{aligned}$$



see V2 Connected by V1 (1993).
~~e) For the case that there is an original solution satisfying $\bar{y}_{ij} - \bar{y}_{ji} = 0$, consider a subclass of the above partition ineq. for the undirected~~

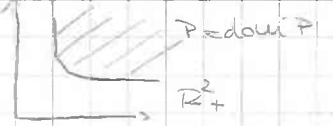
SEP can be separated in polynomial time (although sep. over the exact class of above partition inequalities is NP-complete). \square

Def. 14 (Flow Formulation):

- a) $(STP^{\pm r})$ with z, y
- (i) $z^t(\delta^+(v)) - z^t(\delta^-(v)) = \begin{cases} 1 & v=r \\ 0 & v \neq r, t \\ -1 & v=t \end{cases}$ Flow form. for the STP and root r
- (ii) $z^t \leq y$, $v+t \in E$ flow conservation constraint
- (iii) $z \geq 0$ coupling constraint
- (iv) $y \geq 0$ non-neg. constraint
- (v) $y \in \mathbb{Z}^A$ non-neg. constraint and integrality

(non neg. because of (iii)) $\textcircled{3}$

Facets of $(STP \geq 0)$



Lemma (Facets of up-monotone polyhedra): Let $P = \text{down } \bar{P} \subseteq \mathbb{R}^n_+$ be a non-empty and up-monotone polyhedron (i.e., $x \in P \Rightarrow y \in P \forall y \geq x$). Then

$$\bar{\pi}^T x \geq \pi_0$$

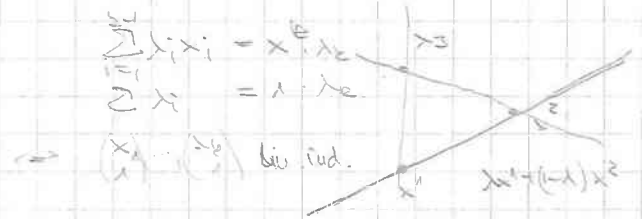
is a non-trivial (i.e., different from $x_j \geq 0$) facet of \bar{P} iff

i) $\bar{\pi} \neq 0, \pi_0 > 0$

ii) $\exists x^1, \dots, x^{|\text{supp}(\bar{\pi})|} \in \bar{P} \cap \{\bar{\pi}^T x = \pi_0\}$ s.t. the matrix

$$\begin{pmatrix} x^1 \cdot \bar{\pi} \\ \vdots \\ x^{|\text{supp}(\bar{\pi})|} \cdot \bar{\pi} \end{pmatrix} \cdot \text{supp}(\bar{\pi})$$

is regular.



Proof:

" \Rightarrow ": i) $\nexists j: x_j = 0 \forall x \in \bar{P} \cap \{\bar{\pi}^T x = \pi_0\} \Rightarrow \bar{\pi} \neq 0 \Rightarrow \pi_0 > 0$

ii) $\bar{\pi} \neq 0, \pi_0 > 0 \Rightarrow 0 \in \{\bar{\pi}^T x = \pi_0\} \Leftrightarrow \begin{pmatrix} x^1 \\ \vdots \\ x^e \end{pmatrix}, \begin{pmatrix} x^e \\ \vdots \\ x^e \end{pmatrix}$ lin indep.

$(\bar{\pi}, \pi_0)$ facet of $\bar{P} \Leftrightarrow \exists x^1, \dots, x^n$ aff. indep. vectors $x_i \in \bar{P} \cap \{\bar{\pi}^T x = \pi_0\}$

$0 \notin \{\bar{\pi}^T x = \pi_0\} = \text{aff}\{\bar{\pi}^T x = \pi_0\} \Leftrightarrow x^1, \dots, x^n, 0$ aff. indep.

$\Leftrightarrow x^1, \dots, x^n$ lin. indep.

$\Rightarrow \text{rank} \begin{pmatrix} x^1 \cdot \bar{\pi} \\ \vdots \\ x^n \cdot \bar{\pi} \end{pmatrix} \cdot \text{supp}(\bar{\pi}) = |\text{supp}(\bar{\pi})|$
 w.l.o.g. $\text{rank} \begin{pmatrix} x^1 \cdot \bar{\pi} \\ \vdots \\ x^n \cdot \bar{\pi} \end{pmatrix} \cdot \text{supp}(\bar{\pi}) = |\text{supp}(\bar{\pi})|$

" \Leftarrow " Let w.l.o.g. $\text{supp}(\bar{\pi}) = \{1, \dots, k\}$. Then

$\text{rank} \begin{pmatrix} x^1 \cdot \bar{\pi} \\ \vdots \\ x^k \cdot \bar{\pi} \end{pmatrix} \cdot \{1, \dots, k\} = k \Rightarrow \text{rank} \begin{pmatrix} x^1 \cdot \bar{\pi} \\ \vdots \\ x^k \cdot \bar{\pi} \\ x^{k+1} \cdot \bar{\pi} = x^{k+1} \cdot e_1 + e_1 \cdot \bar{\pi} \\ \vdots \\ x^n \cdot \bar{\pi} = x^n \cdot e_1 + e_1 \cdot \bar{\pi} \end{pmatrix} = n$

$\Rightarrow x^1, \dots, x^n$ lin indep.

$\Rightarrow x^1, \dots, x^n$ aff. indep. and

$\bar{\pi}^T x^i = \pi_0, i=1, \dots, n. \quad \square$

Theorem (Some facts of $\mathcal{P}(STP^{uc})$ and $\mathcal{T}(STP^{uc})$): def $\mathcal{P}(STP^{uc}) \neq \emptyset$, $\mathcal{T}(STP^{uc}) \neq \emptyset$.

- i) $x_w \geq 0$ def. a fact of $\mathcal{P}(STP^{uc})$ iff $\{e\}$ is not a Steiner cut
- ii) $x_a \geq 0$ def. a fact of $\mathcal{P}(STP^{uc})$ iff $\{a\}$ is not a directed Steiner cut.
- iii) $x(S(V_1; V_2)) \geq 1$ def. a fact of $\mathcal{P}(STP^{uc})$ iff $S(V_1; V_2)$ is a uni. Steiner cut
- iv) $x(S(V_1; V_2)) \geq 1$ def. a fact of $\mathcal{T}(STP^{uc})$ iff $S(V_1; V_2)$ is a directed Steiner cut such that

a) $\mathcal{D}(V_1)$ contains an arborescence A_r with root r that spans $V_1 \cap (V_1; V_2)$

b) $\mathcal{D}(V_2)$ contains for every $v \in V_2 \cap (V_1; V_2)$ an arborescence A_v with root v that spans $V_2 \cap \mathcal{R}$.

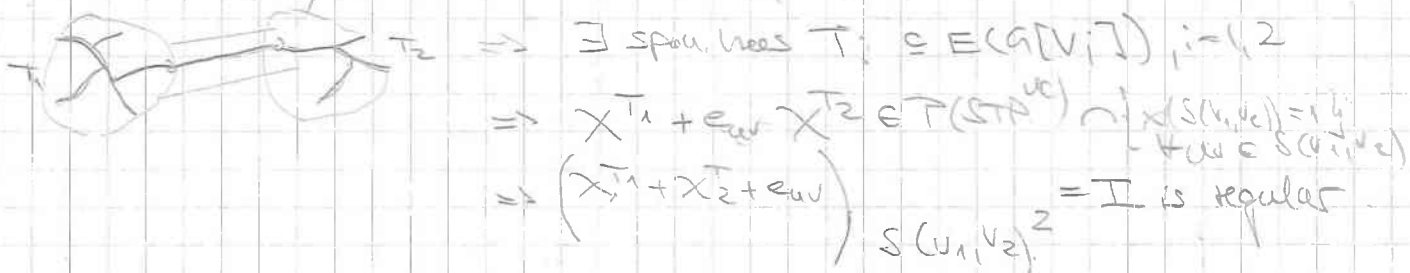
Proof:

i) $\exists x \in \mathcal{T}(STP^{uc}) : x_e = 0 \Rightarrow \underbrace{\{x, x + e_f, f \neq e\}}_{|E| \text{ aff. ind. vectors}} \in \mathcal{T}(STP^{uc}) \cap \{x_e = 0\}$

ii) Analogous to i).

iii) " \Rightarrow " Sect 6, ex. 1, Part 2.

" \Leftarrow " $S(V_1; V_2)$ uni \Rightarrow $G[V_1], G[V_2]$ (connected)



The lemma yields the statement

iv) " \Leftarrow " Analogous to iii) using $x^{A_r} + e_{uv} + x^{A_v}, uv \in S(V_1; V_2)$.
 " \Rightarrow " let $a = uv \in S(V_1; V_2)$.

Suppose \nexists span. tree in $\mathcal{D}(V_1) \Rightarrow \chi^T(S(V_1; V_2)) \geq 2$

\nexists uni. Steiner tree $T \ni uv \Rightarrow \mathcal{T}(STP^{uc}) \cap \{x(S(V_1; V_2)) = 1\} = \emptyset \neq \emptyset$.

Suppose \nexists span. arborescence A_v in $\mathcal{D}(V_2) \Rightarrow$ \square

Prop 15: a) $\text{proj}_Y P(\text{STP}^F) = P(\text{STP}^{\infty})$, c) $P(\text{STP}^{F+}) \subseteq P(\text{STP}^F)$

b) $\text{proj}_Y P_{LP}(\text{STP}^F) = P_{LP}(\text{STP}^{\infty})$, d) $P_{LP}(\text{STP}^{F+}) \subseteq P_{LP}(\text{STP}^F)$

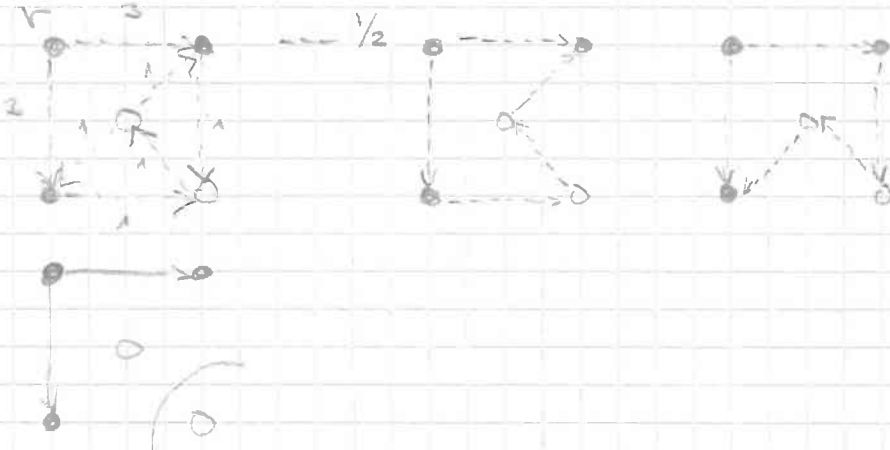
Proof: a) clear b) Max-flow-min-cut, c), d) clear.

Def. 14 (Farkas Lemma)

b) $(\text{STP}^{F+}) = (\text{STP}^F)$

(vi) $x(S^-(v)) \leq x(S^+(v)) \quad \forall v \in V \setminus R$ flow balance cond. \square

Ex. 5 (Flow balance constraints, Pözzia [2003]):



$v_{LP}(\text{ST}^F) = 5/2$

$v_{LP}(\text{ST}^{F+}) = 6 \quad \square$

Def. 16 (Common Flow Formulation, Pözzia [2003]): $(Y_{r,t}, x)_{r,t \in R}$ variables

(STP^{CF}) min $c^T x$

(i) $y^{r,t}(S^+(v)) - y^{r,t}(S^-(v)) = 1 \quad \forall r,t \in R$

(ii) $y^{r,t} \leq y^{r,s} + y^{s,t} \quad \forall v,s,t \in R$

(iii) $y_{ij}^{r,s} \leq y_{ij}^{r,t} + y_{ij}^{s,t} \quad \forall r,s,t \in R, j \in A$

(iv) $y^{r,B}(S^-(v)) \leq y^{r,B}(S^+(v)) \quad \forall v \in R, B \subseteq R \setminus v, v \in V \setminus (B \cup R)$

(v) $y^{r,B} \leq y^{r,C} \quad \forall v \in R, B \subseteq C \subseteq R \setminus v$

(vi) $y_{ij}^{r,R} + y_{ij}^{r,R} \leq x_{ij} \quad \forall v \in R, j \in E$

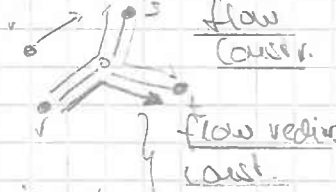
(vii) $y_{ij}^{r,R} = 0 \quad \forall v \in R, j \in E$

(viii) $y_{ij} \geq 0$

(ix) $x \geq 0$

(x) $x \in \mathbb{Z}^E$

Common flow form for forest SP



Common flow bal. cond.

capacity (coupling)

non-neg. cond.

int. cond.

Prop 17: a) $\text{proj}_X P(\text{STP}^{CF}) = P(\text{STP}^{F+})$

b) $\text{proj}_X P_{LP}(\text{STP}^{CF}) \subseteq P(\text{STP}^{F+})$

Proof: a) i) generates dual flow, ii), iii), vii) detect it since dual $y_{ij}^{r,t} = c_{ij}^{r,t}$

$\forall r,t$, (iv) penalize flow imbalance, (v), (vi) transport it to x .

b) Consider a fixed root r ; $|B|=1$ and $|B|=|R|-1$:

where $\sigma \succ \gamma$

(i) $\gamma^{v,t}(\delta^+(v)) - \gamma^{v,t}(\delta^-(v)) = 1 \quad \forall t \in \mathbb{R}$

(ii) ✓

(iii) ✓

(iv) $\gamma^{v,t}(\delta^-(v)) \leq \gamma^{v,t}(\delta^+(v)) \quad \forall v \neq v,t$

$\gamma^{v,R}(\delta^-(v)) \leq \gamma^{v,R}(\delta^+(v)) \quad \forall v \in V \setminus R$

(v) $\gamma^{v,t} \leq \gamma^{v,R} \quad \forall t \in \mathbb{R} \setminus V$

(vi) ✓

(vii) $\gamma^{r,r} = 0$

(viii) $\gamma \geq 0$

(ix) ✓

(x) ✓

Identifying $\gamma^{v,t}$ and z^+ , and $\gamma^{v,R}$ and γ , the formulations are easily seen to be equivalent. □

Rem. 18: No example is known for which $P_{LP}(STP^{eff}) \neq P(STP^{eff})$, but also no proof of equality is known. □

5.12.11

4 Symmetric extended Formulation

We consider in this section

$K_n = G = (V, E)$ the complete graph on n nodes

$\mathcal{F} \subseteq 2^E$ a family of edge sets

$P(x) := \{x \in \mathbb{R}^E : x = \sum \lambda^F x^F, \sum \lambda^F = 1, \lambda^F \geq 0\}$ the \mathcal{F} -polytope
 $= \text{conv}\{x^F : F \in \mathcal{F}\}$

$\Pi(M) := \{\pi: M \rightarrow M \text{ bijection}\}$ permutations of a set M .

Def. 4.1: Let $\pi \in \Pi(V)$ be a permutation of the node set V .

i) $\pi(ij) := \pi(i)\pi(j) \quad \forall ij \in E$

ii) $\pi(\mathcal{F}) := \{\pi(ij) : ij \in F\} \quad \forall F \in \mathcal{F}$

iii) $\pi(P(x)) := \text{conv}\{x^{\pi(F)} : F \in \mathcal{F}\}$

Def. 4.2: $P(x, \gamma) \in \mathbb{R}^{\text{Ext}}$
is an extended formulation of $P(x)$ iff $P(x, \gamma)|_x = P(x)$.

Def. 4.3: Let $P(x, \gamma) \in \mathbb{R}^{\text{Ext}}$ be an extended formulation of $P(x)$.

i) $P(x)$ is symmetric $\Leftrightarrow \pi(P(x)) = P(x)$.

ii) $P(x, \gamma)$ " " " " Let $P(x, \gamma) : \Leftrightarrow \forall \pi \in \Pi(V) : \exists \pi' \in \Pi(\text{Ext}) : (\pi, \pi') (P(x, \gamma)) = P(x, \gamma)$.

Rem. 4.4: $P(x)$ is symmetric if all nodes play the same role, $P(x, \gamma)$ is symmetric if any node permutation of can be extended to the new variables

ex. 4.5: The spanning tree, matching, perfect matching (for even n), TSP polytopes in their natural variables are symmetric.

Thm 4.6 (Yannakakis [1991]): There is no symmetric extended formulation of the perfect matching polytope having subexponential size.

Proof: Much harder than a fact proof. The main steps are:

- i) Transform the symmetric extended formulation to standard form (equality constraints + non-negative variables)
- ii) Show that every variable "depends" on "few" nodes.
- iii) Reduce to an LP with a specific set of variables, which is at least as powerful.
- iv) Show that this LP does not work.

Thm. 47. (Yamabe's [1981]): There is no symmetric extended formulation of the TSP polytope having subexponential size.

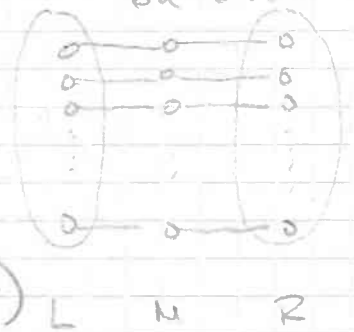
Proof: Suppose $P(x, \pi)$ is such a formulation. Consider $K = (V, E)$ on and let

$$L := \{l_1, \dots, l_{2n}\} = \{1, \dots, 2n\}$$

$$U := \{u_1, \dots, u_{2n}\} = \{2n+1, \dots, 4n\}$$

$$R := \{r_1, \dots, r_{2n}\} = \{4n+1, \dots, 6n\}$$

$$\tilde{E} = E(L) \cup \{e_i, u_i\}_{i=1}^{2n} \cup \{u_i, r_i\}_{i=1}^{2n} \cup E(R)$$



Then

$$\left(\frac{P(x, \pi) \cap \{x_{ij} = 0 : ij \notin \tilde{E}\}}{E(L)} \right) \Big|_X = \text{conv} \left\{ x^H : H \text{ Hamiltonian circuit in } (V, \tilde{E}) \right\} \Big|_{E(L)}$$

$$= \text{conv} \left\{ x^H : H \text{ perfect matching in } (L, E(L)) \right\}$$

$$= K_{2n} \quad \square$$

→ goto p. 11

5. Heuristics and Approximation Algorithms for the Undirected STP

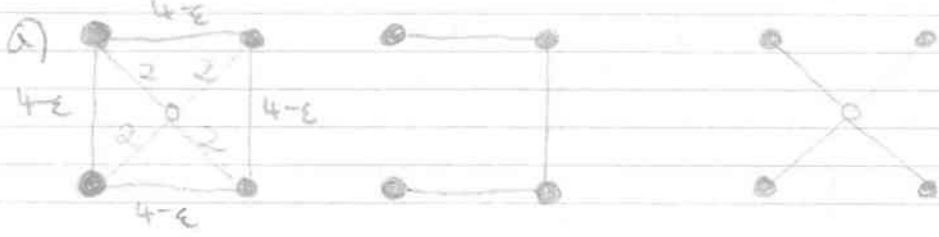
Alg 5.1: Shortest-Path Heuristic (Tabuchi & Makino [1980]): 02.01.202

Input: Graph $G=(V,E)$ edge weights $c \in \mathbb{Q}_+^E$, terminals $R \subseteq V$

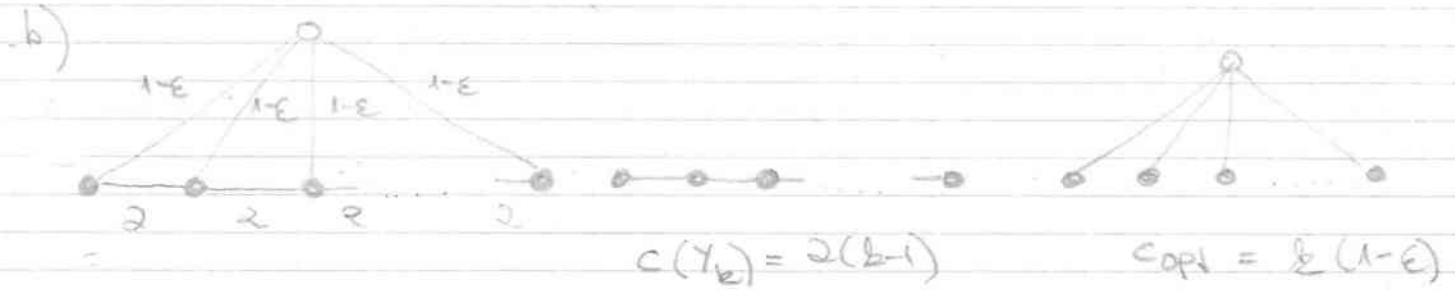
Output: Steiner set $Y \subseteq E$

1. $i \leftarrow 0, T_0 \leftarrow \emptyset$
2. $i \leftarrow i+1$
3. $v_i \leftarrow \arg \min_{v \notin T_{i-1}} \text{dist}(v, T_{i-1}), P_i \leftarrow \text{associated } (v_i, T_{i-1})\text{-path, b.t.d.}$
4. $T_i \leftarrow T_{i-1} \cup P_i$
5. IF $R \subseteq T$ then Output T_i , end.
 goto 2.

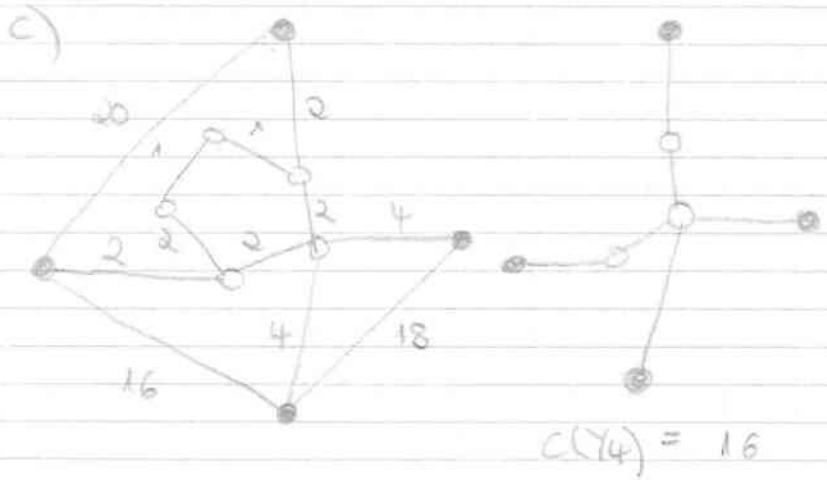
Example 5.2:



• minimal $C(Y_4) = 12 - 3\epsilon$ $c_{opt} = 8$ $\frac{C(Y_4)}{c_{opt}} = \frac{12 - 3\epsilon}{8} \rightarrow \frac{3}{2}$ as $\epsilon \rightarrow 0$



$C(Y_b) = 2(b-1) = \frac{2(b-1)}{b(1-\epsilon)} c_{opt} \rightarrow \frac{2(b-1)}{b}$



$C(Y_4) = 16$

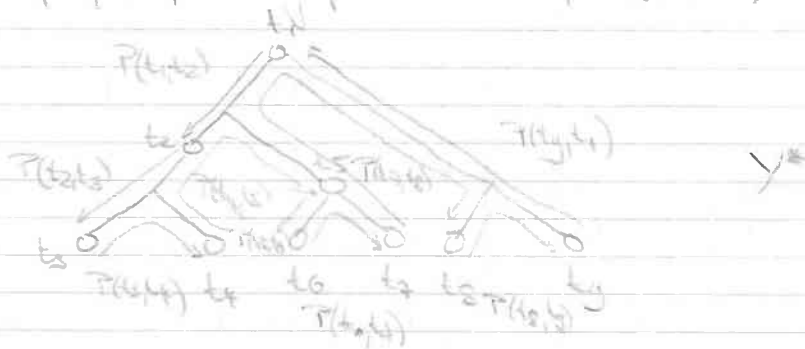
Theorem 5.3 Let G, c, R be an instance of MSTP, $|R| = k$, c_{opt} the weight of a minimum Steiner tree γ^* , and γ the output of Alg 5.1. Then:

$$c(\gamma) \leq 2 c_{opt} \frac{k-1}{k}.$$

Proof:

Consider γ . W.l.o.g. let $v_i = i$, $i = 1, \dots, k$, and $V_i = \{1, \dots, i\} = V(\gamma) \cap R$.

Consider γ^* . Choose $t_i \in R$ and traverse γ^* in words, visiting terminals in words t_1, \dots, t_k , along paths $P(t_i, t_{i+1})$:



Then $P(t_1, t_2), P(t_2, t_3), \dots, P(t_{k-1}, t_k)$ is an Euler tour visiting every edge of γ^* twice and once

$$\sum_{i=1}^{k-1} c(P(t_i, t_{i+1})) = 2 c_{opt}$$

Let w.l.o.g. t_1 such that $c(P(t_1, t_k)) = \max_{i=1}^{k-1} c(P(t_i, t_{i+1}))$, then

$$\sum_{i=1}^{k-1} c(P(t_i, t_{i+1})) \leq 2 c_{opt} \frac{k-1}{k}.$$

We will now establish a 1:1-mapping

$$\bullet : \{2, \dots, k\} \rightarrow \{t_1, \dots, t_{k-1}\}, \text{ i.e.}$$

$$\frac{P_i}{\gamma} \mapsto \underbrace{P(t_i, t_{i+1})}_{\gamma} =: P_i^*$$

such that $\{t_i, t_{i+1}\} \in V_{i-1} \times (R \setminus V_{i-1})$. (1)

Then $c(P_i) = \min_{S \subset V_{i-1}, t \in R \setminus V_{i-1}} c(CT(S, t)) \leq c(CT(V_{i-1}, t_{i+1}))$

$$\begin{aligned} \Rightarrow c(\gamma) &= \sum_{i=2}^k c(P_i) \leq \sum_{i=2}^k c(CT(V_{i-1}, t_{i+1})) \\ &= \sum_{i=1}^{k-1} c(P_{t_i, t_{i+1}}) \leq 2 c_{opt} \frac{k-1}{k}. \end{aligned}$$

The mapping is established using the method of Borzabanyan et al.

The sequence t_1, \dots, t_k is a permutation of $1, \dots, k$. Let $l \geq 2$ and

$$t(p_1), \dots, t(p_l), \dots, t(q_1)$$

a maximal subsequence of t_1, \dots, t_k such that $t(p_1), \dots, t(q_l) \geq l$ and let

$$i^* := \begin{cases} q(i) & \text{if } p(i)=1 \text{ or } t(q(i)+1) > t(p(i)-1) \\ p(i)-1 & \text{if } q(i)=k \text{ or } t(p(i)-1) > t(q(i)+1) \end{cases}, \quad i^*+1 = \begin{cases} q(i)+1 & \text{if } i^* = q(i) \\ p(i) & \text{if } i^* = p(i)-1 \end{cases}$$

and denote by (i^*, i^{**}) a critical pair for i to other words: The critical pair marks the highest index into the subsequence

$$t(p(i)), \dots, t(i), \dots, t(q(i)), \dots \quad \text{if it exists}$$

$$t(p(i-1)), \dots, t(i-1), \dots, t(q(i)), \dots \quad \text{if } i > t(p(i)-1) > t(q(i)+1)$$

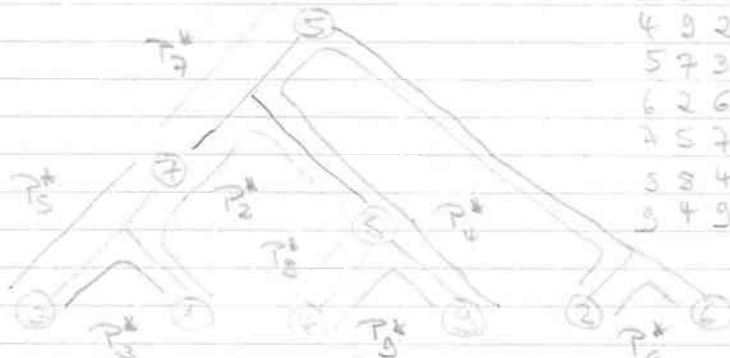
$$t(p(i-1)), \dots, t(i-1), \dots, t(q(i-1)), \dots \quad \text{if } i > t(q(i)-1) > t(p(i)+1)$$

Ex. 5.4: $l=9$

5, 7, 3, 1, 8, 4, 9, 2, 6

$i \quad i^* \quad t(i) \quad t(i+1)$

2	4	1	8
3	2	3	1
4	7	9	2
5	2	7	3
6	2	2	6
7	1	5	7
8	5	2	4
9	6	4	9



i	$t(i)$	5	7	3	1	8	4	9	2	6
1										
2	1	2				8	4	9	2	6
3	3	1	5	7	3*					
4	9	2				3	4	9*		
5	7	3	5	7*						
6	2	6								9*
7	5	7		7*						
8	3	4				8*				
9	4	9								

Proof (cont'd): - Now $i > \dots \in V_{i-1}, i \leq \dots \in R \setminus V_{i-1}$ implies (1).

It remains to be shown that $*$ is a bijection.

Suppose not and w.l.o.g. $i < j$ have $i^* = j^*$.

look dead $\begin{cases} t(i) < t(i+1) \Rightarrow t(i) = t(p(i)-1) \\ t(i) > t(i+1) \Rightarrow t(i) = t(q(i)) \end{cases}$

Case 1: $t(i) = t(p(i)-1)$: $t(i^*) < t(p(i))$ $j \quad i \Rightarrow j^* = i$

$$\begin{matrix} t(p(i)-1) & t(p(i)) \\ \uparrow & \uparrow \\ t(i) & t(j) \\ \uparrow & \uparrow \\ t(i^*) & t(j^*) \\ \uparrow & \uparrow \\ t(p(i)-1) & t(p(i)) \end{matrix}$$

$\underbrace{t(i^*)}_{< i} \quad \underbrace{t(j^*)}_{\geq i} \quad \underbrace{t(j)}_{< j}$

case 2: Symmetry.

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Alg. 5.5: Minimum-Spanning-Tree Heuristic (Kou, Markowsky & Barman [1981])

Input: graph $G = (V, E)$, edge weights $c_e \in \mathbb{Q}_+$, terminals $R \subseteq V$

Output: Steiner set $Y \subseteq E$

1. Compute complete graph $G^* = K_{|R|}$ on nodes R with edge weights

$$c_{ij}^* = \min_{P_{ij}} c(P)$$

P_{ij} - path in G

let $P_{ij}^* = \arg \min_{P_{ij}} c(P)$

P_{ij}^* - path in G

2. Compute MST Y^* in G^* , let $H = \bigcup_{e \in Y^*} P(e)$.

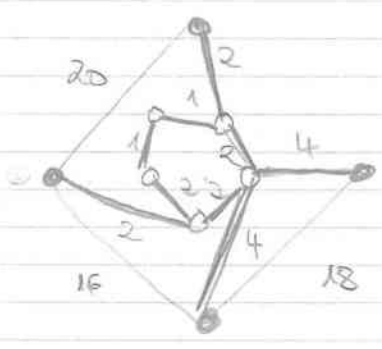
3. Compute MST Y in H .

4. While \exists leaf $v \in V(Y) \setminus R$

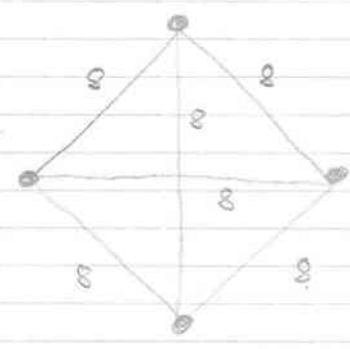
$$Y \leftarrow Y \setminus \{v\}$$

5. Output Y .

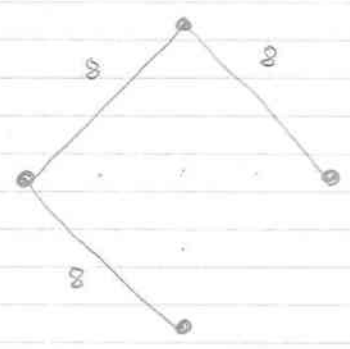
Ex 5.6:



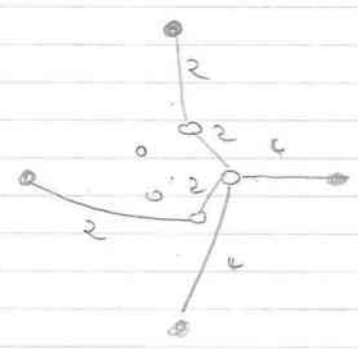
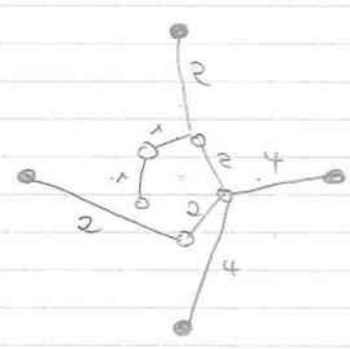
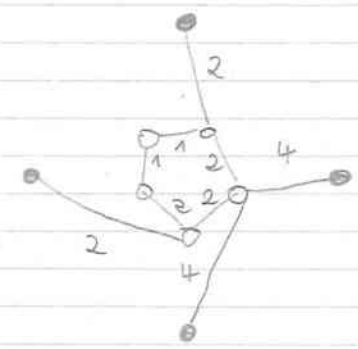
G



G^*



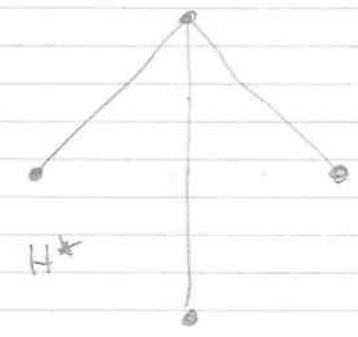
Y^*



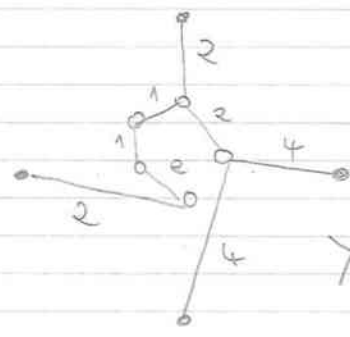
or: H

Y

$Y, c(Y) = 16$



H^*

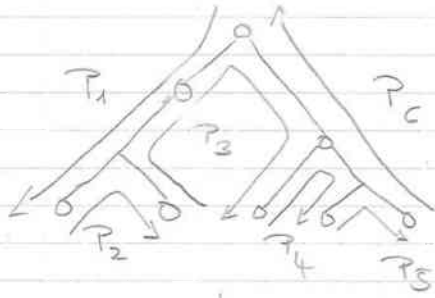


$Y, c(Y) = 18$

Thm 5.7: Let G, c, R be an instance of LSTP, and t the minimal number of leaves of an optimal Steiner tree γ of weight c_{opt} , and γ^* the output of Alg. 5.5. Then

$$c(\gamma^*) \leq 2 c_{opt} \frac{t-1}{t}$$

Proof: Choose a leaf $w \in R$ of γ^* as a root node, associate an Euler-tour E^* with γ^* and subdivide it into paths P_1, \dots, P_t along the leaves of γ^* :



W.l.o.g. let $c(P_t) = \max_{i=1}^t c(P_i)$. Every path P_i corresponds to an edge e_i in G^* , (e_1, \dots, e_t) is a cycle in G^* , (e_1, \dots, e_t) is a tree in G^* , and $H = P_1 \cup \dots \cup P_t$ is a Steiner set. Then

$$c(\gamma^*) \leq c(H) \leq 2 c_{opt} \frac{t-1}{t}. \quad \square$$

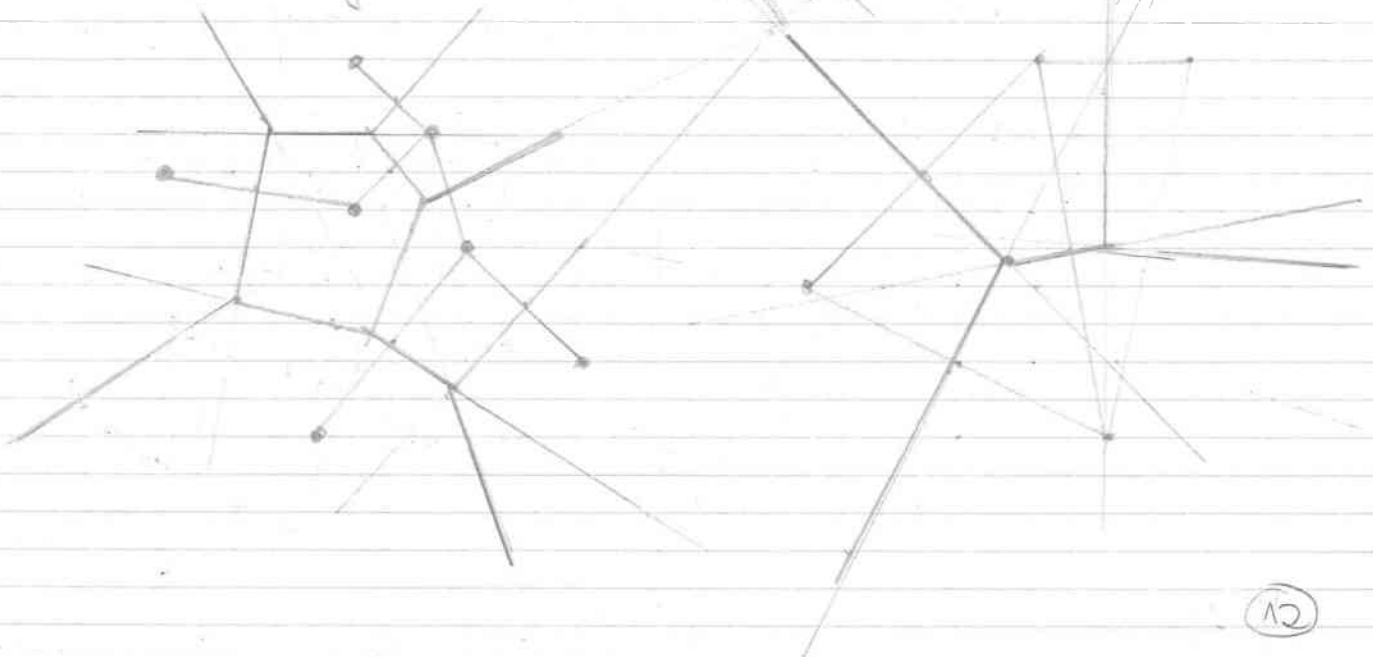
12.12.11

Thm 5.8: The running time of Alg. 5.5 is $O(n^3 \log n + nm)$.

Proof: There are n shortest path computations, each takes $O(n \log n + m)$. \square

Idea: Improve running time by computing few paths between neighboring nodes using Voronoi regions.

Ex. 5.9: Spanning tree in the plane (Euclidean distances)



Def. 5.10: Let G, c, p be an instance of MSTP.

i) $\Psi(t) := \{u \in V : \text{dist}_c(t, u) = \min_{s \in R} \text{dist}_c(s, u)\}$ $\forall t \in R$ Universal region of t
 s.t. a. such that $\Psi(t) \neq \emptyset$ and $\bigcup_{t \in R} \Psi(t)$ is a partition of V .

ii) $\pi(v) := t$ s.t. $v \in \Psi(t)$.

iii) Define $\bar{G} = (V, \bar{E})$ with edge weights \bar{c} as follows:

$$V := R$$

$$\bar{E} := \{(s, t) \in V^2 : \exists (u, v) \in E \text{ s.t. } u \in \Psi(s), v \in \Psi(t)\}$$

$$\bar{c}_{st} := \min_{u \in \Psi(s)} \text{dist}_c(s, u) + c_{uv} + \min_{v \in \Psi(t)} \text{dist}_c(v, t) \quad \forall s, t \in \bar{E}$$

Lemma 5.11: A MST in \bar{G} is also a MST in G^* .

Proof: Let Y^* be a MST in G^* s.t. $|Y^* \setminus \bar{E}|$ is minimal, and to ease of desc a tree s.t. $\tau(Y^*)$ is minimal. Then Y^* is a MST in G and

$$c^*(Y^*) = \tau(Y^*)$$

Suppose not. Then $\exists (s, t) \in Y^*$ s.t.

$$(i) (s, t) \notin \bar{E} \quad \text{or}$$

$$(ii) \bar{c}_{st} > c^*(s, t)$$

$Y^* \setminus (s, t)$ breaks into 2 components $Y^*_s \ni s, Y^*_t \ni t$.



Let $S = v_0, v_1, \dots, v_r = t$ be a shortest path in G between Universal regions

$$s = \pi(v_0), \pi(v_1), \dots, \pi(v_r) = t$$

$$\Rightarrow \exists i: \pi(v_{i-1}) \in V(Y^*_s), \pi(v_i) \in V(Y^*_t)$$

$$\Rightarrow (\pi(v_{i-1}), \pi(v_i)) \in \bar{E} \text{ and } c^*_{st} \text{ is minimal.}$$

$$c^*_{\pi(v_{i-1})\pi(v_i)} \stackrel{(\text{ii})}{\leq} \bar{c}_{\pi(v_{i-1})\pi(v_i)} \quad (< \text{ if (ii) holds})$$

$$\stackrel{(\text{ii})}{\leq} \text{dist}_c(\pi(v_{i-1}), v_{i-1}) + c_{v_{i-1}v_i} + \text{dist}_c(v_i, \pi(v_i))$$

$$\stackrel{v_0, \dots, v_r \text{ shortest path}}{\leq} \text{dist}_c(s, v_{i-1}) + c_{v_{i-1}v_i} + \text{dist}_c(v_i, t)$$

$$= c^*_{st}$$

$\Rightarrow Y^* \setminus (s, t) \cup \{(\pi(v_{i-1}), \pi(v_i))\} = Y^*$ is a spanning tree in G^* s.t.

$$\left. \begin{aligned} |Y^* \setminus \bar{E}| &> |Y^* \setminus \bar{E}|, \text{ if (i) holds and} \\ c^*(Y^*) &< c^*(Y^*), \text{ if (ii) holds} \end{aligned} \right\} \Rightarrow \text{contradiction}$$

$\Rightarrow Y^*$ is a MST in \bar{G} and $c^*(Y^*) = \tau(Y^*)$.

Consider now a MST \bar{Y} in $\bar{G} \Rightarrow \bar{Y}$ is a MST in G^* and $c^* \leq \bar{c}$

$$\Rightarrow c^*(\bar{Y}) \leq \bar{c}(\bar{Y})$$

$$\Rightarrow c^*(Y^*) = \bar{c}(Y^*) \geq \bar{c}(\bar{Y}) \geq c^*(\bar{Y})$$

$$\Rightarrow c^*(Y^*) = c^*(\bar{Y}) \text{ , i.e. , } \bar{Y} \text{ is a MST in } G^* . \square$$

Lemma 5.12: \bar{G} can be computed in $O(m \log n + m)$ time.

Proof:



\bar{Y} can be computed in $O(m \log n + m)$ time.

Expl.: Run Dijkstra's Alg. in an aux. graph that adds an artificial vertex O to all terminals

via edges of length 0, computing a shortest path tree with root O .

For each $v \in V$ we then know

(i) the Voronoi region $\pi(v)$

(ii) the length $\text{dist}_c(v, \pi(v))$ of the shortest path from v to terminal $\pi(v)$.

$\Rightarrow (u, v) \in E$ generates the potential edge $(\pi(u), \pi(v)) \in \bar{E}$ with weight

$$\bar{c}(\pi(u), \pi(v)) = \text{dist}_c(u, \pi(u)) + c_{uv} + \text{dist}_c(v, \pi(v))$$

The edge is chosen if $\pi(u) \neq \pi(v)$ and the weight is minimal.

We could now loop over $(u, v) \in E$, check if $(\pi(u), \pi(v)) \in \bar{E}$, if not add it, otherwise update $\bar{c}_{\pi(u), \pi(v)}$. This takes $O(E + |R|^2)$ if we store \bar{E} in an adjacency matrix. But we can do better. Compute for each $(u, v) \in E$

$$\left(\min\{\pi(u), \pi(v)\}, \max\{\pi(u), \pi(v)\}, \text{dist}_c(u, \pi(u)) + c_{uv} + \text{dist}_c(v, \pi(v)) \right)$$

and store these 3-tuples in a list of length m . Sort for the second end then for the first component in $O(|R| + m)$ using bucket sort. Then select

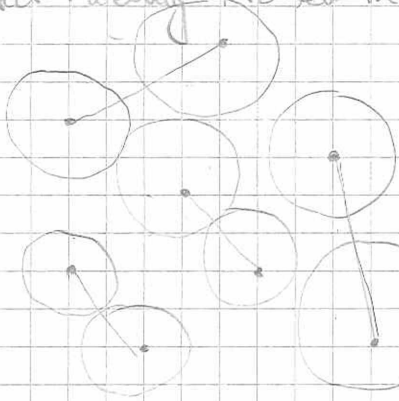
for each $(\pi(u), \pi(v))$ the minimum of the second component in $O(m)$. \square

02.01.12

5. Geometric Duality and Primal-Dual Algorithms (Exercise 10)

5.1. Matching

1. Primal Matching Problem in the plane (Euclidean distances):



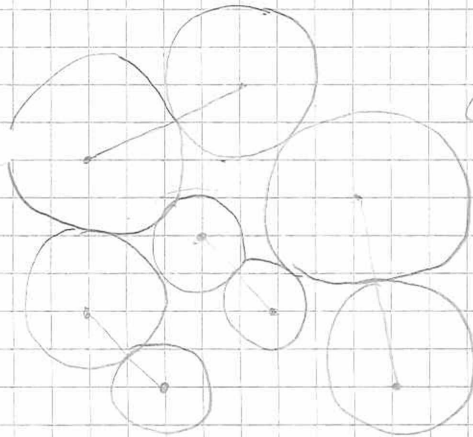
1. Even number of points in the plane

2. Primal Matching M

3. Discs of radii $r_u > 0$ around $u, v \in V$, disjoint

4. $uv \in M \Rightarrow c_{uv} \geq r_u + r_v$

5. $\Rightarrow c(M) \geq r(V)$ ← lower bound



6. $c_{uv} = r_u + r_v \quad \forall uv \in M$

$\Rightarrow c(M) = r(V)$

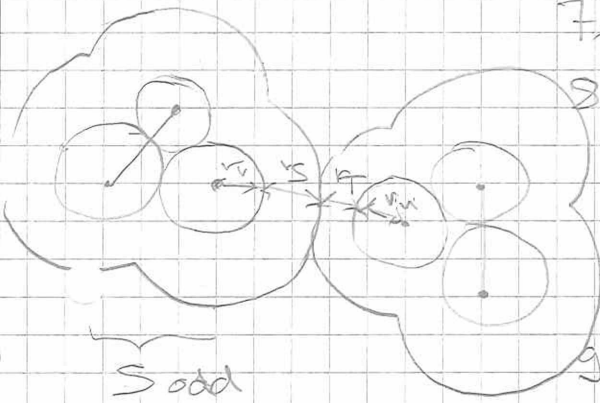
$\Rightarrow M$ optimal

7. Sometimes $c(M) > r(V) \quad \forall M, r$ (Tu)

8. "Goats" of radii $r_s > 0$ around odd sets

$\emptyset \subsetneq S \subsetneq V, |S|$ odd, disjoint, i.e.,

$$\sum_{S(S) \ni e} r_s \leq c_e \quad \forall e \in E$$



9. $uv \in M \Rightarrow c_{uv} \geq \sum_{S(S) \ni u} r_s$ take $\bigcup_{v \in V} S$

$\Rightarrow c(M) \geq r(\bigcup_{S \text{ odd sets}} S)$

10. $c_{uv} = \sum_{S(S) \ni uv} r_s \quad \forall uv \in M$

$\Rightarrow M$ optimal.

11. $\max \sum_{S \in \mathcal{O}} r_s$

$$\sum_{S(S) \ni e} r_s \leq c_e$$

$$r \geq 0$$

Duality

$$= \min \sum c_e x_e$$

$$x(S(S)) \geq 1 \quad \forall S \in \mathcal{O}$$

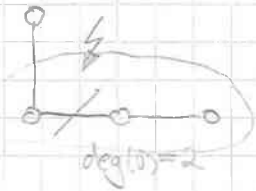
$$x_e \geq 0$$

Edwards

$$= \min \sum c_e x_e$$

$$x(S(S)) \geq 1 \quad \forall S \in \mathcal{O}$$

$$x_e \in \{0, 1\} \quad \forall e \in E$$



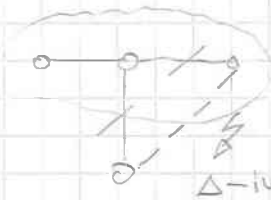
odd set
spanning
TU

$$= \min \sum c_e x_e$$

$$x(S(S)) \geq 1 \quad \forall S \in \mathcal{O}$$

$$x(S(v)) = 1 \quad \forall v \in V$$

$$x_e \in \{0, 1\} \quad \forall e \in E$$

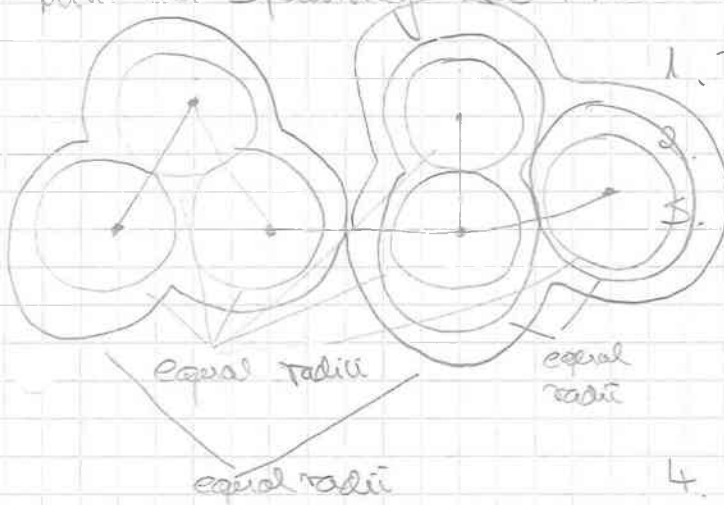


odd set

Δ -inequality

5.2. Spanning Tree

Minimum Spanning Tree Problem (not necessarily in the Euclidean plane)



1. Points with distances (use: Euclidean)

2. Spanning tree γ

3. Moats of radii r_S around node sets

$\emptyset \neq S \neq V$, disjoint, i.e.,

$$\sum_{S(S) \ni e} r_S \leq c_e \quad \forall e \in E$$

$$4. e \in \gamma \Rightarrow c_e \geq \sum_{S(S) \ni e} r_S$$

$$\Rightarrow c(\gamma) \geq \sum_{S(S) \ni e} r_S$$

$$5. c(\gamma) = r(\mathcal{F})$$

$\Rightarrow \gamma$ optimal

$$6. \max_{S \in \mathcal{F}} \sum r_S$$

$$\sum_{S(S) \ni e} r_S \leq c_e$$

$$r \geq 0$$

Duality

$$= \min_{c \in E} \sum_{c \in E} c_e x_e$$

$$x(S(S)) \geq 1 \quad \forall S \in \mathcal{S}$$

$$x \geq 0$$

but mostly <

$$\leq \min_{c \in E} \sum_{c \in E} c_e x_e$$

$$x(S(S)) \geq 1 \quad \forall S \in \mathcal{S}$$

$$x_e \in \{0, 1\} \quad \forall e \in E$$

Choose c & V arbitrarily.

$$\max_{w \in \mathcal{S}} \sum_{c \in E} r_c$$

$$\sum_{c \in E} r_c \leq c_e \quad \forall e \in E$$

$$\sum_{c \in \mathcal{S}} r_c = \alpha \quad \forall v \in V$$

$$r \geq 0$$

Duality

$$= \min_{c \in E} \sum_{c \in E} c_e x_e$$

$$x(S(S)) + y(S) \geq \begin{cases} 2, & w \notin S \\ 0, & w \in S \end{cases} \quad \forall S \in \mathcal{S}$$

$$y(V) = 0$$

$$x \geq 0$$

Primal Dual

"Tight bound"

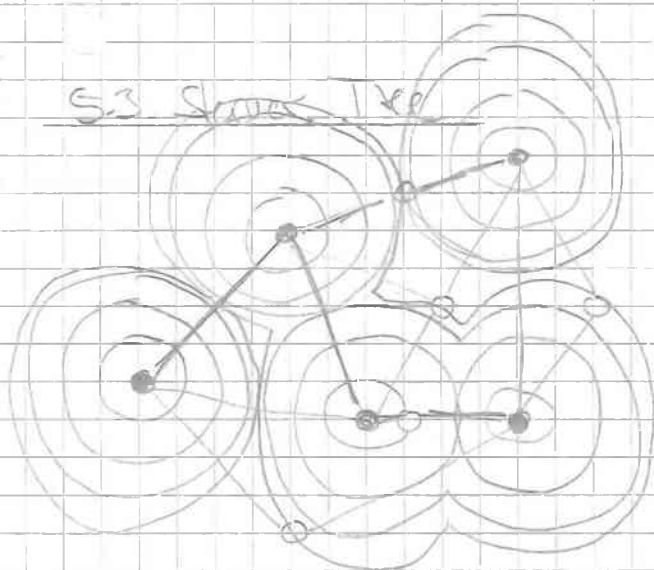
and $y_v = x(S^+(v)) - x(S^-(v))$

$$= \min_{c \in E} \sum_{c \in E} c_e x_e$$

$$x(S(S)) \geq 1 \quad \forall S \in \mathcal{S}$$

$$x_e \in \{0, 1\} \quad \forall e \in E$$

5.3 Steiner Tree



Steiner tree problem (undirected, in the plane)

1. Terminals R and Steiner nodes $V \setminus R$, nodes V
2. Steiner tree γ including a tree
3. Nodes of radius r_s around Steiner and sets \mathcal{S}

$$\emptyset \neq S \cap R \neq R, S \in V, \text{ disjoint}$$

$$\sum_{c \in E} r_c \leq c_e \quad \forall e \in E$$

$$4. e \in \gamma \Rightarrow c_e \geq \sum_{S(S) \ni e} r_s$$

$$\Rightarrow c(\gamma) \geq \sum_{S \in \mathcal{S}} r_s$$

$$5. \max \sum_{S \subseteq E} r_S \quad (2)$$

$$\sum_{S(S) \subseteq E} r_S \leq c_e \quad \forall e \in E$$

$$r \geq 0$$

$$= \min \sum_e c_e x_e$$

$$x(S(S)) \geq 1 \quad \forall S \subseteq E$$

$$x \geq 0$$

$$\stackrel{\text{weakly}}{\leq} \min \sum_e c_e x_e \quad (1)$$

Alg. 5.3.1: Primal-dual Alg

for a given USFP

Input: G, c, r

Output: γ st.

γ_γ is feas. for (1)

r feas. for (2)

1. $\mathcal{F} \leftarrow \emptyset$ Steiner forest

$\mathcal{T}(\mathcal{F}) := \{T \mid T \neq \emptyset, T \subseteq E\}$ components of Steiner forest

$\mathcal{M}(T) \leftarrow \{S \subseteq V(T)\}$ $\forall T \in \mathcal{T}(\mathcal{F})$ local sets around and inside T

$\mathcal{M}(\mathcal{F}) = \bigcup_{T \in \mathcal{T}(\mathcal{F})} \mathcal{M}(T)$

$\mathcal{M} \leftarrow \mathcal{M}(\mathcal{F})$

$\gamma \leftarrow \emptyset$ Steiner tree

$r = 0$

$\bar{r} = 0$

2. While γ is not a Steiner tree

raise r_S uniformly by Δc $\forall S = \delta(V(T)), T \in \mathcal{T}(\mathcal{F})$ until

$\sum_{S \subseteq E} r_S = c_{uv}$ for some edge $uv \in E$

(two components collide)

if uv connects $T_i, T_j \in \mathcal{F}$, $i \in V(T_i) \cap R, j \in V(T_j) \cap R$ then

$\mathcal{F} \leftarrow \mathcal{F} \cup \{uv\}$, merge T_i, T_j to T_{ij}

$\mathcal{M}(T_{ij}) \leftarrow \mathcal{M}(T_i) \cup \mathcal{M}(T_j) \cup \delta(V(T_{ij}))$

$\mathcal{M} \leftarrow \mathcal{M} \cup \delta(V(T_{ij}))$

$\gamma \leftarrow \gamma \cup p$, $p \in T_j$ does path that connects i and j ^{disjuncts}

else if w.l.o.g. $u \in T_i, e \neq i, i \in V(T_i) \cap R$

$\mathbb{F} \leftarrow \mathbb{F} \cup \{u, j\}$, merge T_i and u to $T_{i,u}$

$$\mathcal{M}(T_{i,u}) \leftarrow \mathcal{M}(T_i) \cup \delta(V(T_{i,u}))$$

end if

$$T \leftarrow T + \Delta T$$

Lemma 5.3.2: At any time T and any $T \in \mathcal{T}(\mathbb{F})$:

$$c(T \cap \gamma) \leq 2[r(\mathcal{M}(T)) - T]$$

Proof: At $T=0$ this is correct.

1. Components T_i and T_j collide at time τ .

$$c(T_{ij} \cap \gamma) = c(T_i \cap \gamma) + c(T_j \cap \gamma) + 2\tau$$

$$r(\mathcal{M}(T_{ij})) = r(\mathcal{M}(T_i)) + r(\mathcal{M}(T_j)) + 0$$

$$\rightarrow c(T_{ij} \cap \gamma) = c(T_i \cap \gamma) + c(T_j \cap \gamma) + 2\tau$$

$$\leq 2[r(\mathcal{M}(T_i)) - \tau] + 2[r(\mathcal{M}(T_j)) - \tau] + 2\tau$$

$$= 2[r(\mathcal{M}(T_i)) + r(\mathcal{M}(T_j)) - \tau]$$

$$= 2[r(\mathcal{M}(T_{ij})) - \tau]$$

2. There is no collision for $t \in [\tau, \tau + \Delta T[$.

$$c(T_i \cap \gamma) \equiv \text{const}$$

$$r(\mathcal{M}(T_i)) - t = r(\mathcal{M}(T_i)) + (t - \tau) - t = r(\mathcal{M}(T_i)) - \tau$$

Theorem 5.3.3: Alg 5.3.1 yields γ, r st.

$$c(\gamma) \leq 2r(\mathcal{M}) \left(1 - \frac{1}{|R|}\right)$$

Proof: By construction, γ and r are feasible after time T_{final} .

$$\text{Note } r_{T+\Delta T}(\mathcal{C}) - r_T(\mathcal{C}) \leq |R| \cdot \Delta T \text{ for any real step } \Delta T$$

$$\Rightarrow r_{T_{\text{final}}}(\mathcal{C}) \leq |R| T_{\text{final}}$$

$$\Rightarrow T_{\text{final}} \geq \frac{r_{T_{\text{final}}}(\mathcal{C})}{|R|} = \frac{r_{\text{final}}(\mathcal{M})}{|R|}$$

Lemma 5.3.2

$$\begin{aligned} \Rightarrow c(\gamma) &\leq 2 \left[r(\mathcal{M}) - T_{\text{final}} \right] \\ &\leq 2 \left[r(\mathcal{M}) - \frac{r(\mathcal{M})}{|R|} \right] \\ &= 2 r(\mathcal{M}) \left(1 - \frac{1}{|R|} \right) \quad \square \end{aligned}$$

Q. 5.3.4 :

